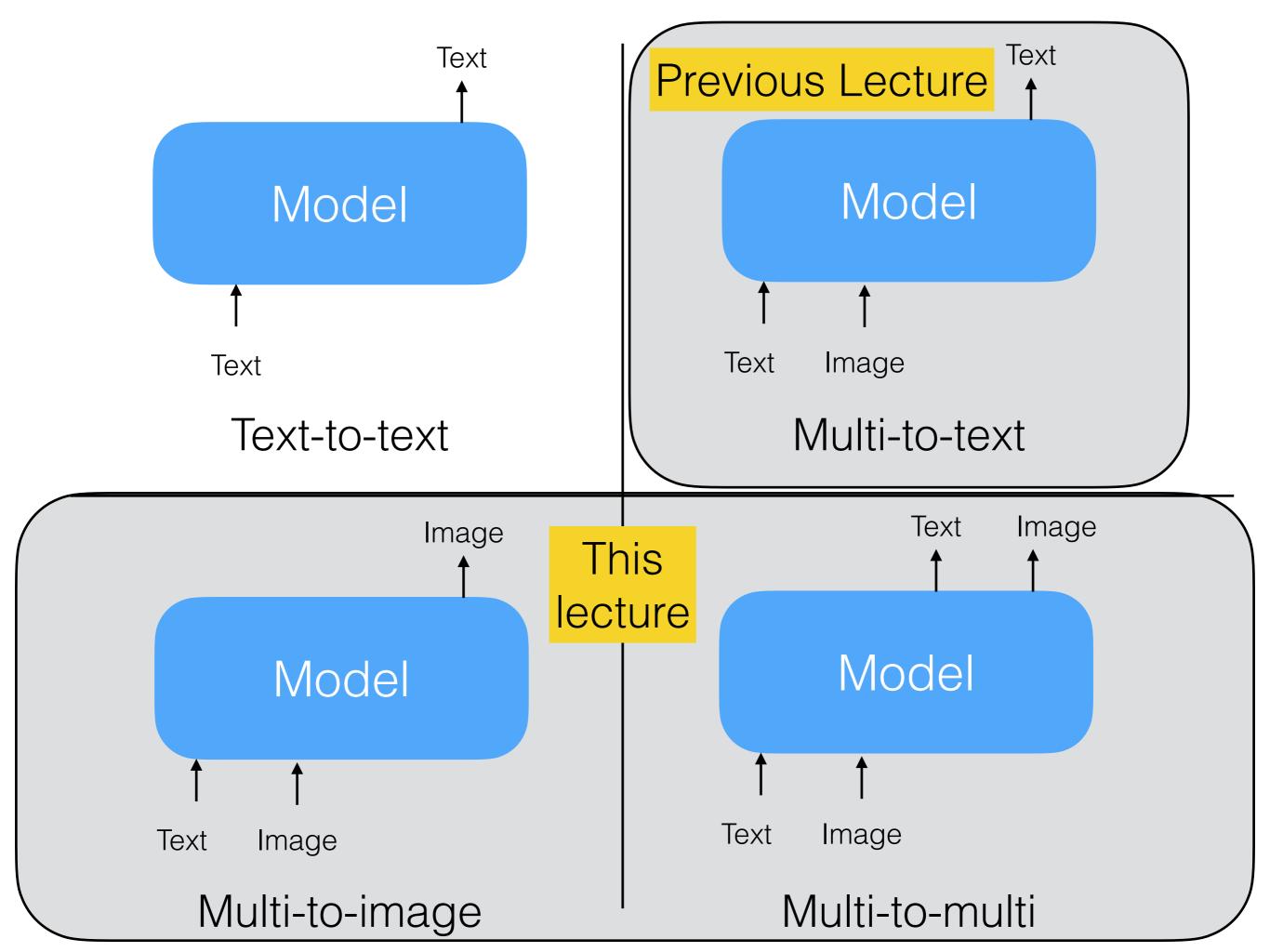
CS11-711 Advanced NLP

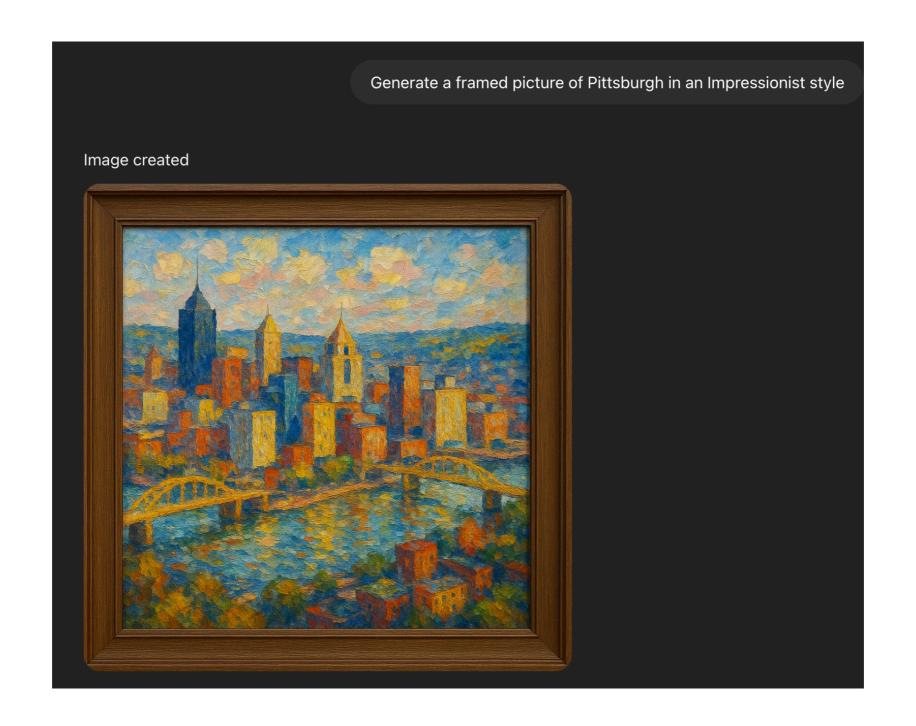
Multimodal Modeling II

Sean Welleck

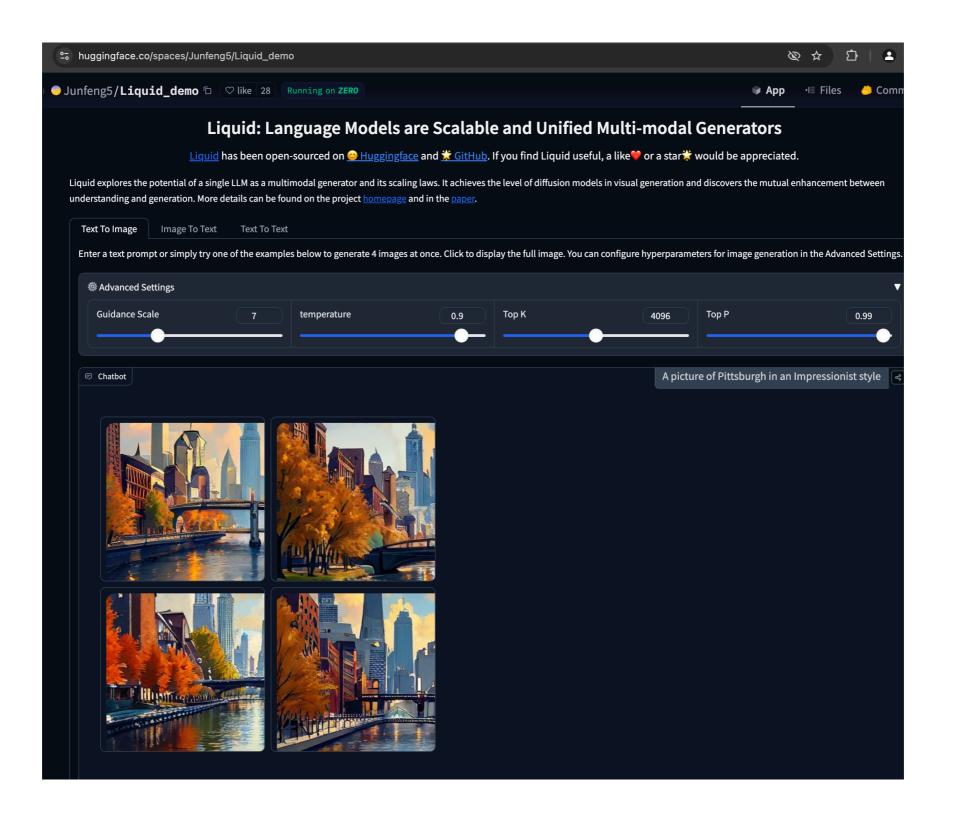


https://cmu-l3.github.io/anlp-spring2025/

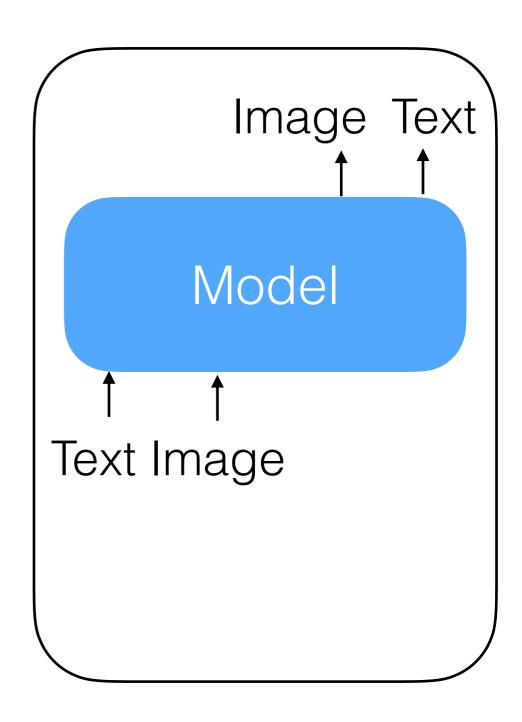




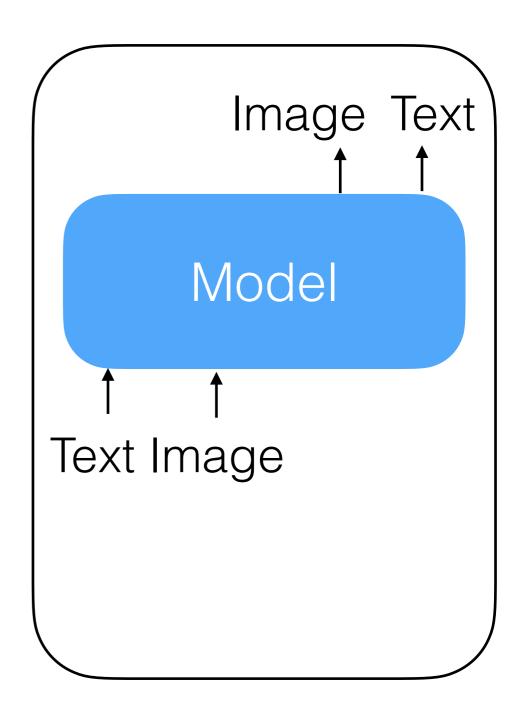
Example: ChatGPT 40



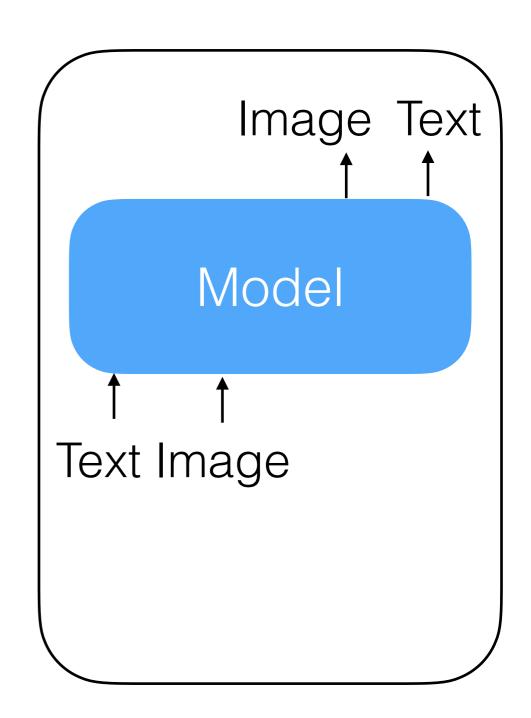
Example: Liquid



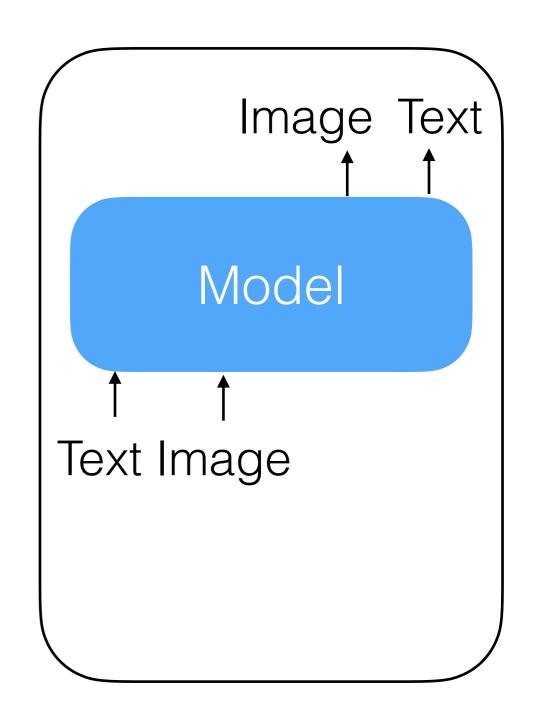
 Basic generative modeling paradigms



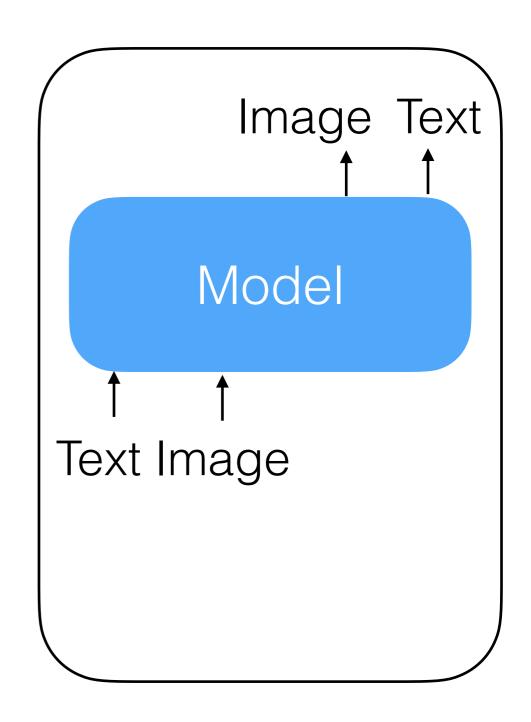
- Basic generative modeling paradigms
- Autoregressive modeling of pixels

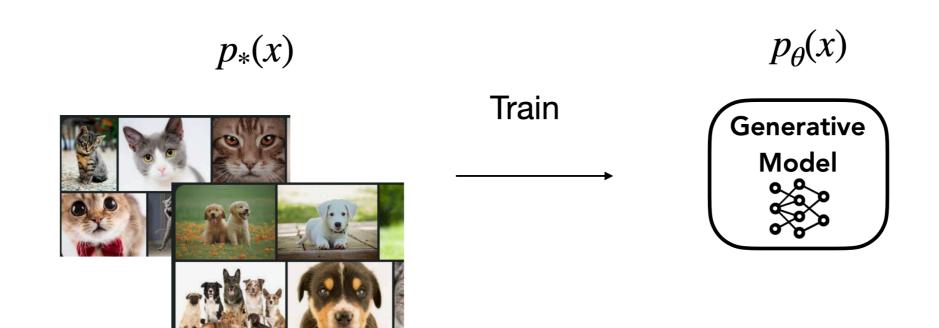


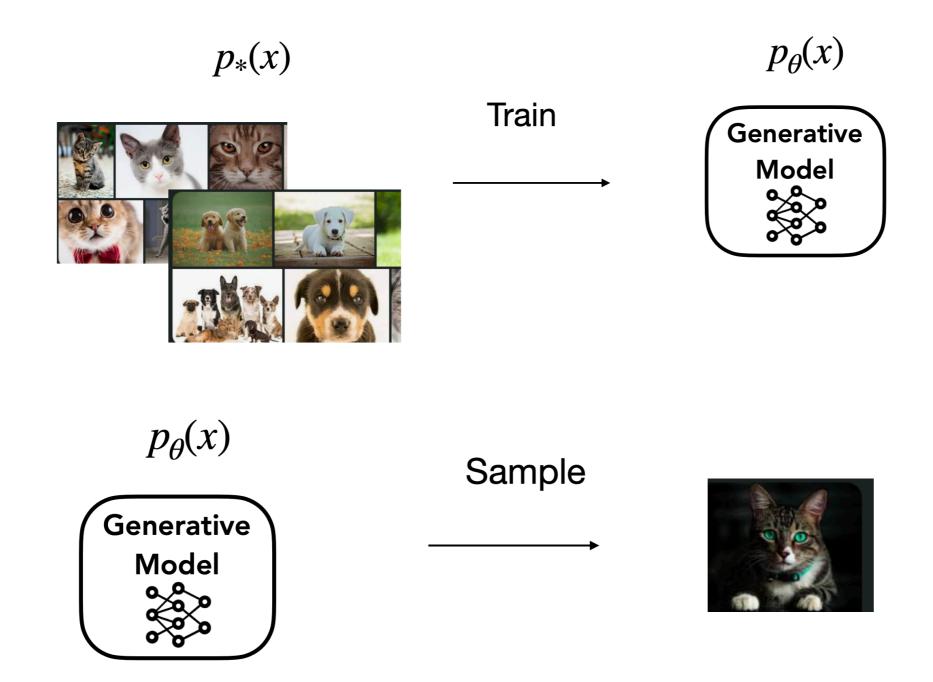
- Basic generative modeling paradigms
- Autoregressive modeling of pixels
- Autoregressive modeling of "image tokens"



- Basic generative modeling paradigms
- Autoregressive modeling of pixels
- Autoregressive modeling of "image tokens"
- Other paradigms

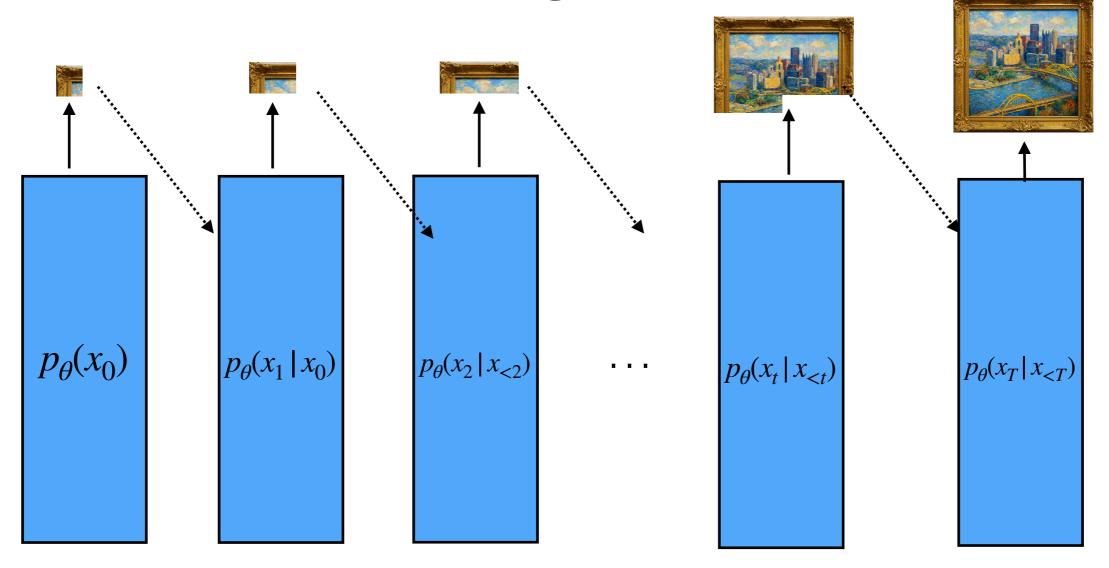






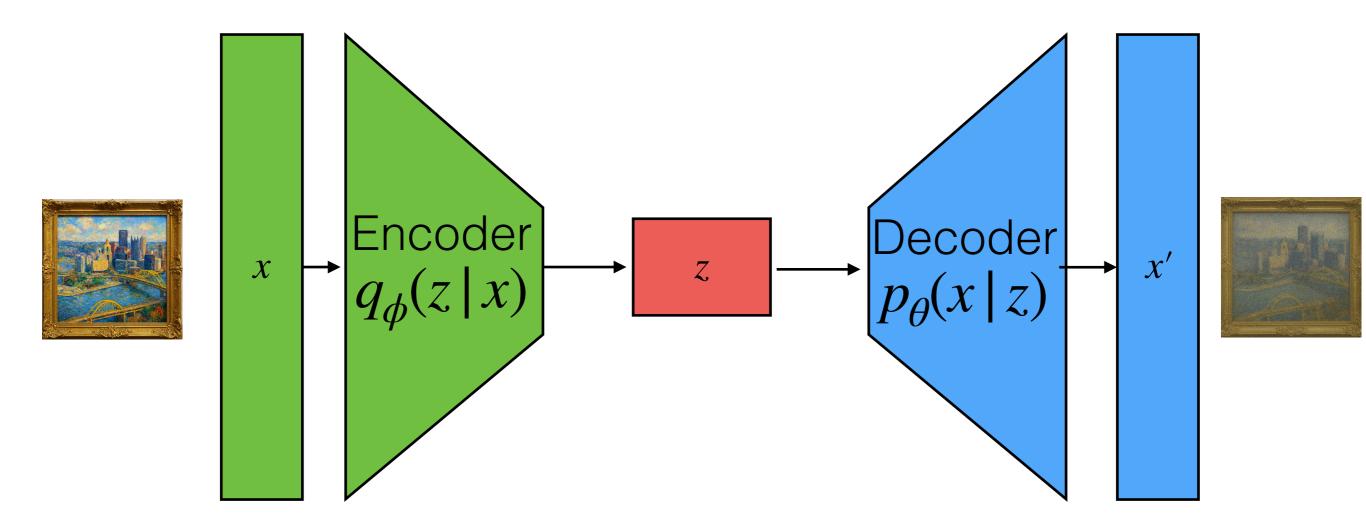
- Autoregressive
- Variational auto-encoder (VAE)
- Generative adversarial networks (GAN)
- Diffusion models

Autoregressive



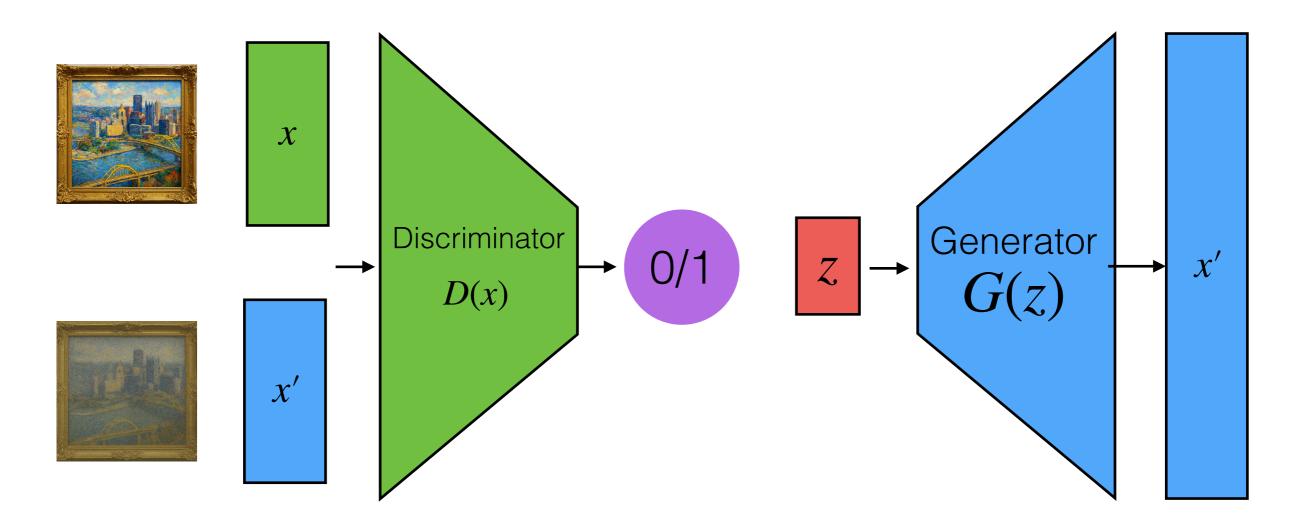
 Generate one dimension (e.g., token, pixel) at a time given the previous ones

Variational Auto-encoders (VAE)



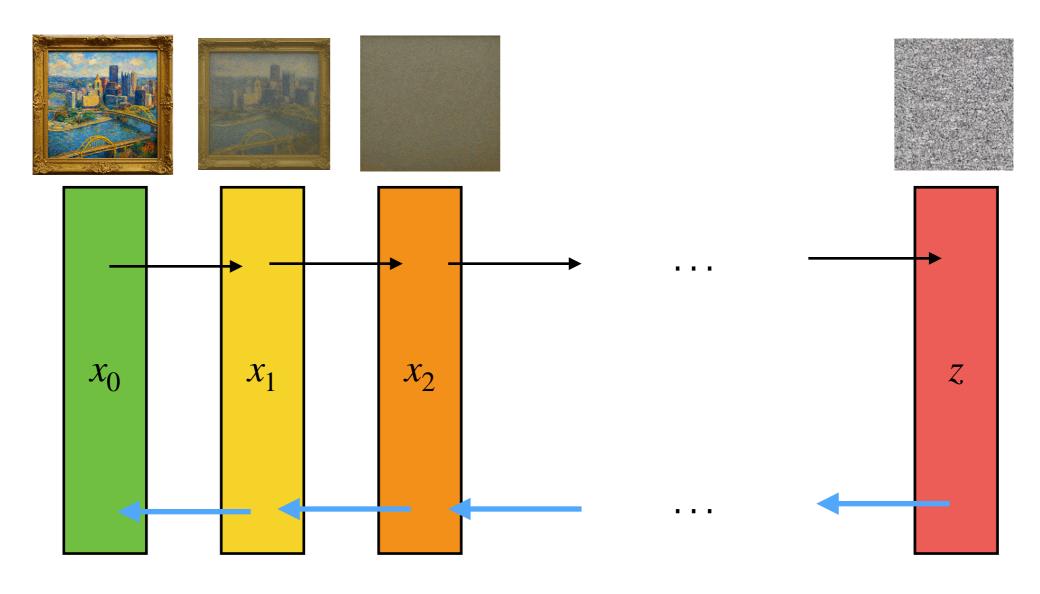
 Learn to reconstruct the image by compressing it into a vector and uncompressing it

Generative adversarial networks (GAN)

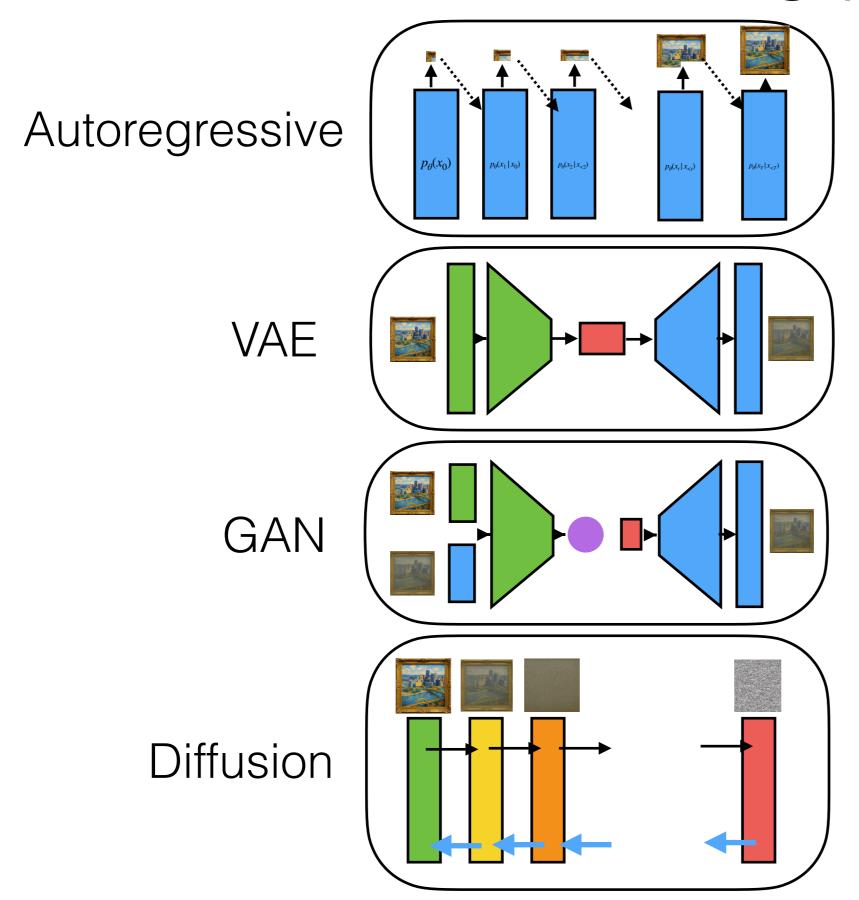


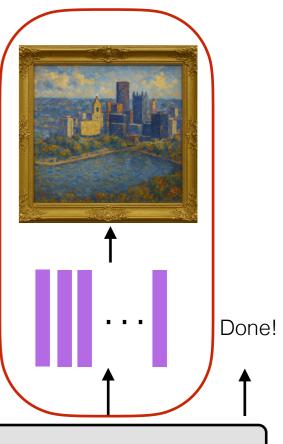
 Learn to generate an image by fooling a discriminator that detects whether an image is fake

Diffusion models



 Gradually add noise to an image, then learn to de-noise





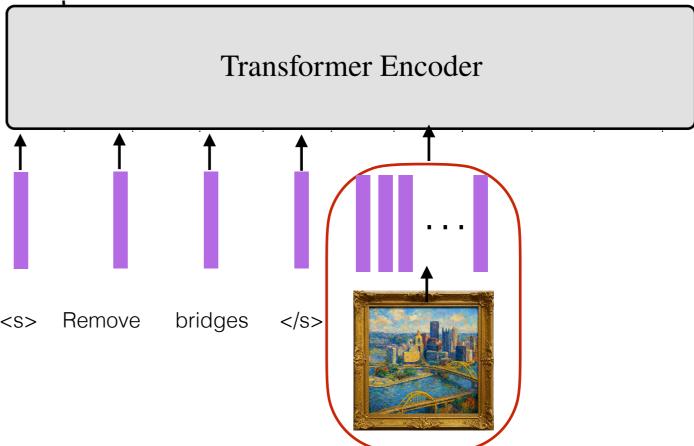
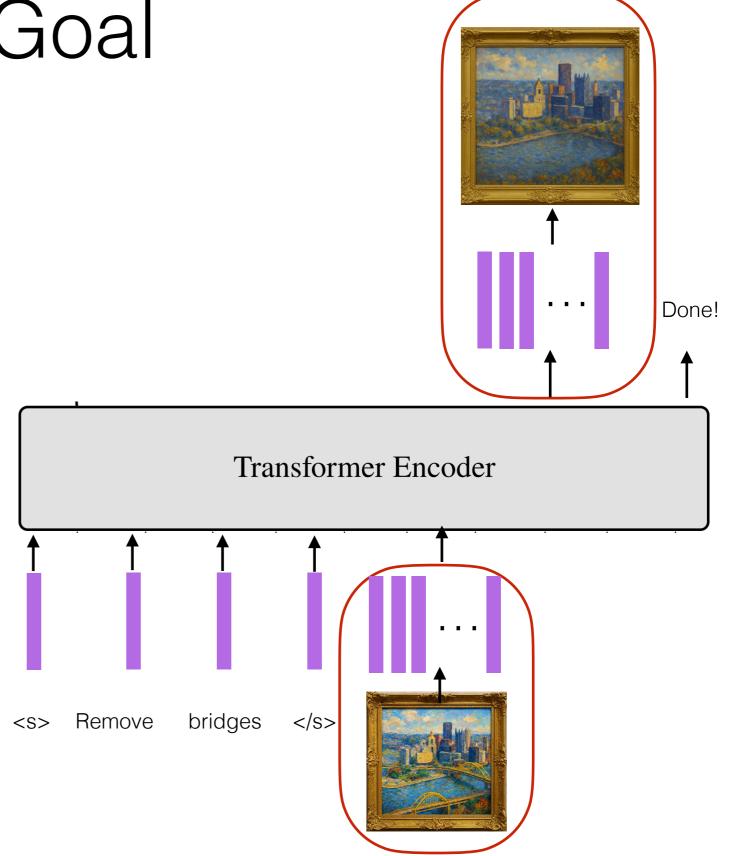
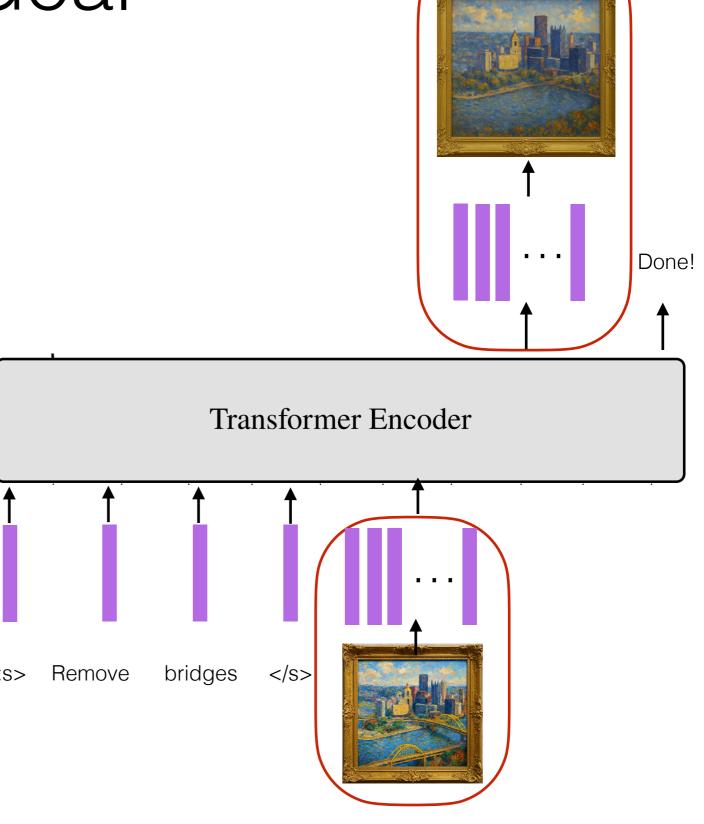


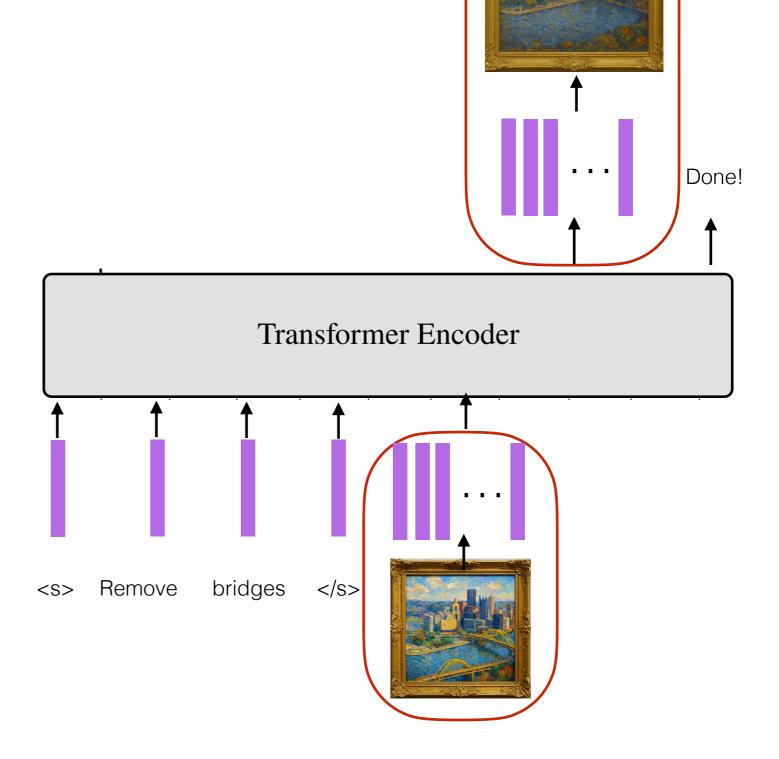
Image tokenizer



- Image tokenizer
- Image "de-tokenizer"



- Image tokenizer
- Image "de-tokenizer"
- Single Transformer for text and image



- Attempt 1: use a standard auto-regressive model
 - Tokenizer: individual pixels
 - De-tokenizer: generate individual pixels, no detokenizer needed

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 - VQ-GAN

- Basic idea: treat an image as a sequence of pixels
 - Learn a language model over the pixel sequences

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$$x_{\text{img}} \in \mathbb{R}^{H \times W \times C} \rightarrow x_1, ..., x_T$$

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$$x_t \in \{1, 2, \dots, 256\}$$

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 - Learn a language model over the pixel sequences

•
$$x_{\text{img}} \in \mathbb{R}^{H \times W \times C} \rightarrow x_1, ..., x_T$$

•
$$x_t \in \{1, 2, \dots, 256\}$$

Given a dataset of sequences:

$$\mathscr{L}_{MLE} = \sum_{t=1}^{T} -\log p_{\theta}(x_t | x_{< t})$$

Example: PixelRNN

[van den Oord 2016]



Figure 1. Image completions sampled from a PixelRNN.

Example: PixelCNN

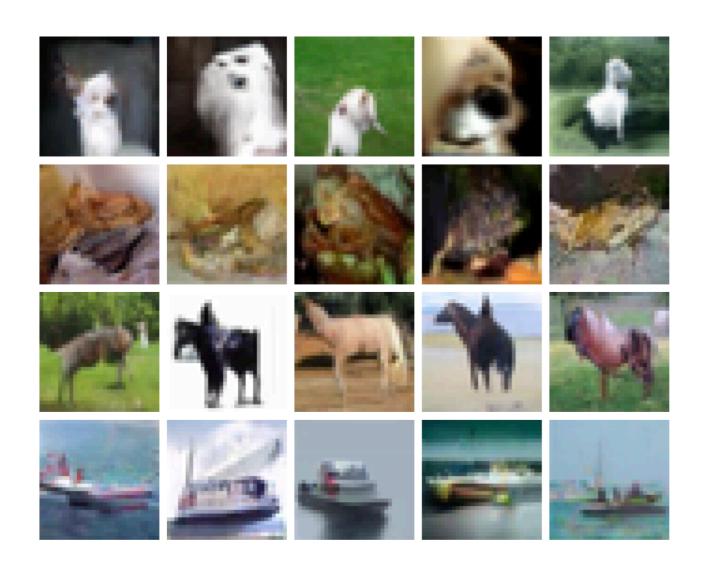
[van den Oord 2016]

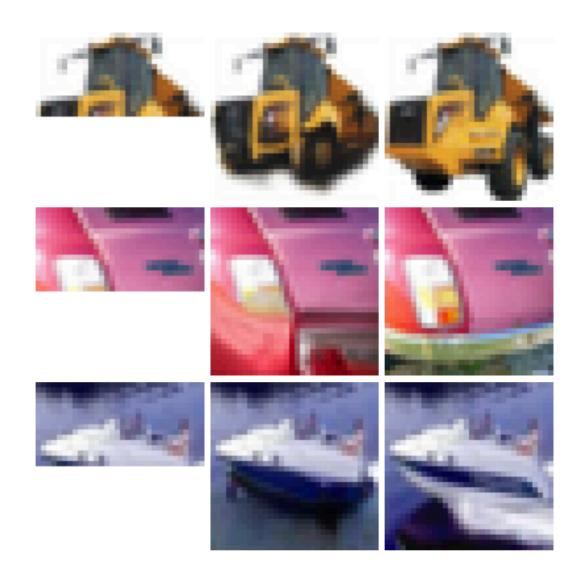


Lhasa Apso (dog)

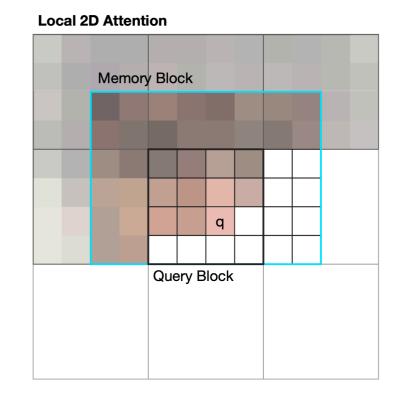
Example: Image Transformer

[Parmar et al 2018]





- Key challenge: sequence length
 - 1024 x 1024 image with 3 channels (RGB)
 - 3 million tokens

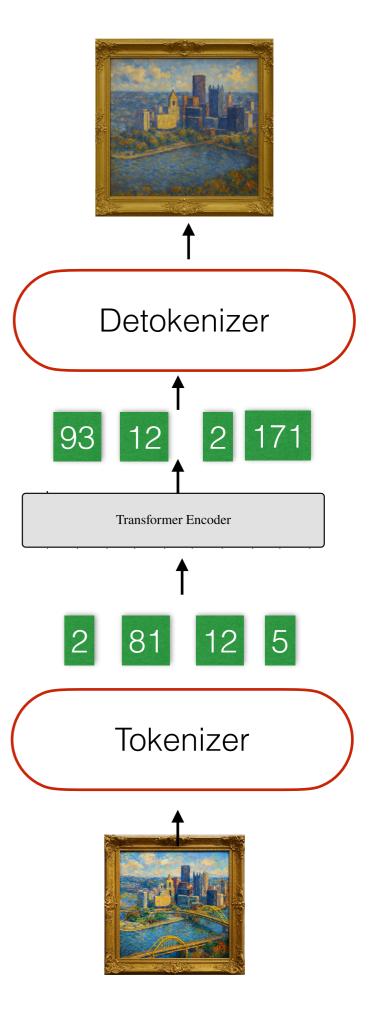


Typically involved alternative memory-efficient attention patterns

- Attempt 1: use a standard auto-regressive model
- Attempt 2: learn a discrete tokenizer / de-tokenizer
 - Vector-quantized VAE (VQ-VAE)
 - VQ-GAN

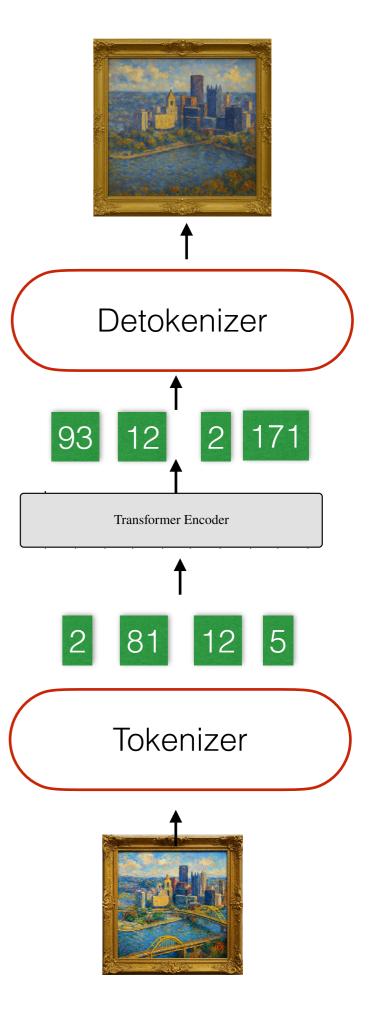
Idea

 Learn a tokenizer that compactly represents an image as a sequence of discrete tokens.



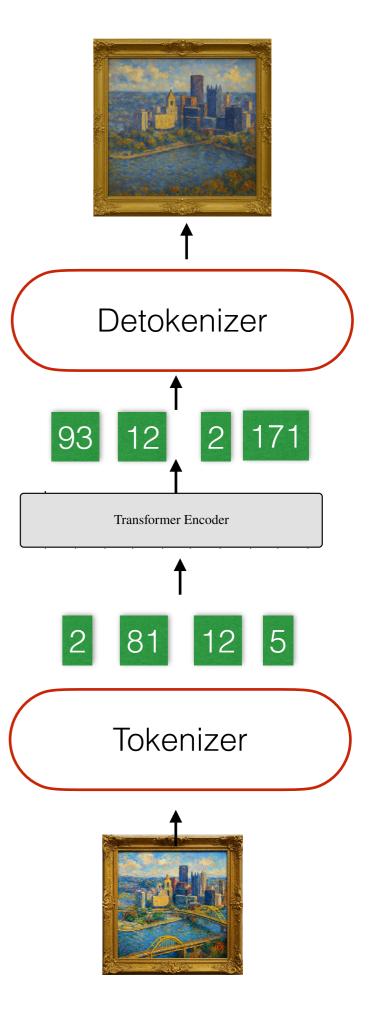
Idea

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- Example:



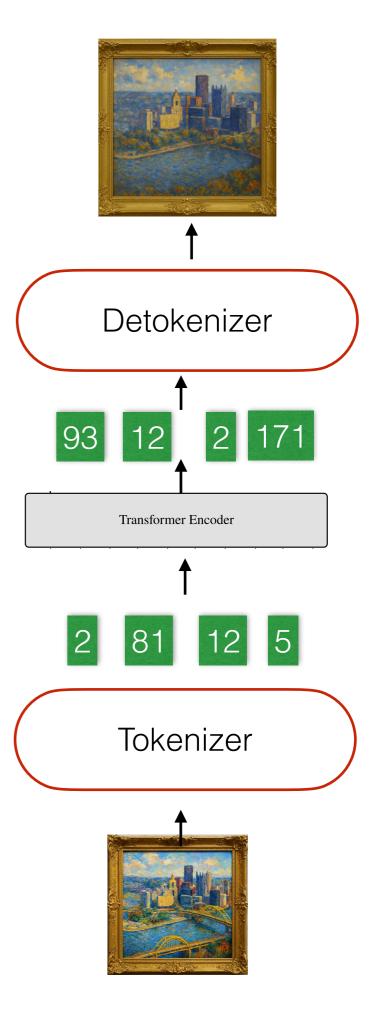
Idea

- Learn a tokenizer that compactly represents an image as a sequence of discrete tokens.
- Example:
 - Vocabulary: 8,000 token ids



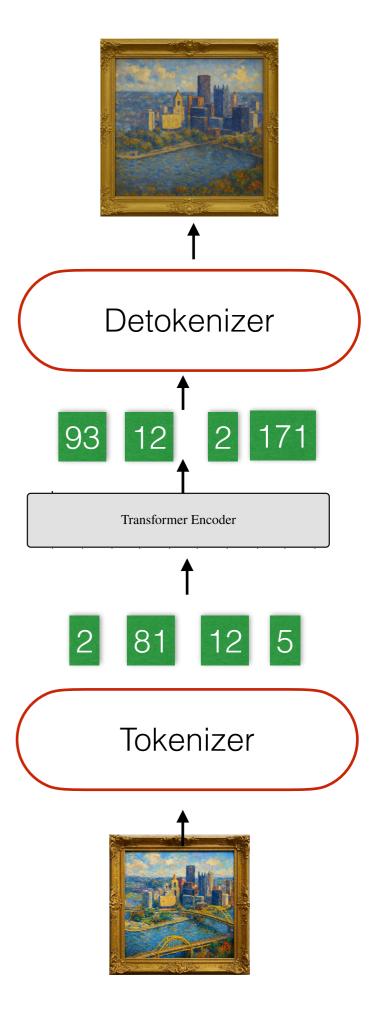
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Idea

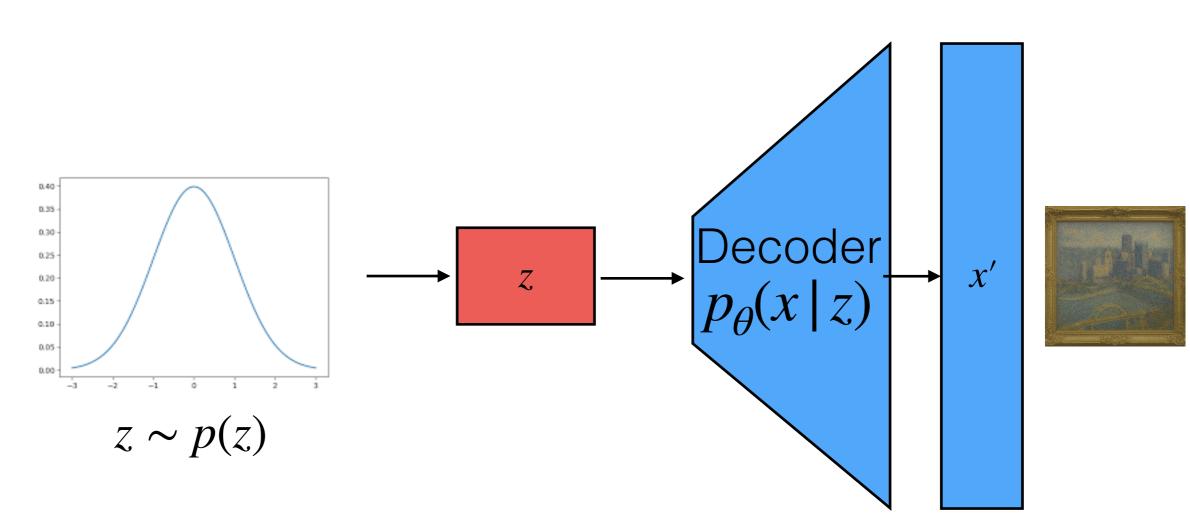
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- Example:
 - Vocabulary: 8,000 token ids
 - Image: sequence of 1024 tokens
- Approach: VQ-VAE



VAE Encoder

 Learn to reconstruct the image by compressing it into a vector and uncompressing it

VAE



 After training, generate by sampling a latent vector from the prior and passing it to the decoder

[Kingma & Welling 2013]

• **Goal**: learn to compress data (like images) into a low-dimensional representation z, and then reconstruct or generate new data with it

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- Assume that data is generated as follows:
 - First sample a latent variable $z \sim p(z)$
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- The encoder maps data x into a latent variable, $q_{\phi}(z \mid x)$

[Kingma & Welling 2013]

• Train by balancing two goals:

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 - Reconstruct the input well:

[Kingma & Welling 2013]

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Reconstruction loss: $-\log p(x \mid z)$

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Keep z values well behaved:

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Makes the encoder's output distribution close to a standard Gaussian

[Kingma & Welling 2013]

• Final loss:

[Kingma & Welling 2013]

Final loss:

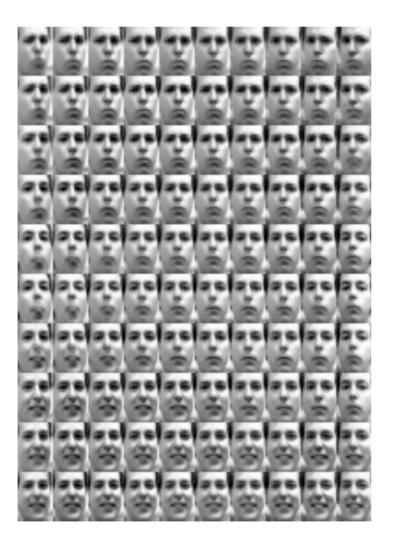
$$\mathcal{L}_{VAE}(x) = -\mathbb{E}_{q(z|x)} \left[\log p(x|z) \right] + D_{KL}(q(z|x)||\mathcal{N}(0,I))$$

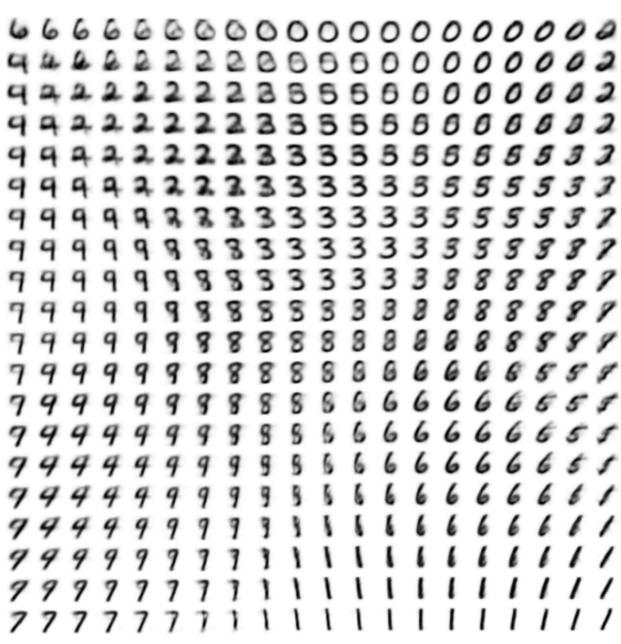
[Kingma & Welling 2013]

Final loss:

$$\mathcal{L}_{VAE}(x) = -\mathbb{E}_{q(z|x)} \left[\log p(x|z) \right] + D_{KL}(q(z|x)||\mathcal{N}(0,I))$$

 Principled formulation and derivation based on variational inference: see [Kingma & Welling 2013]

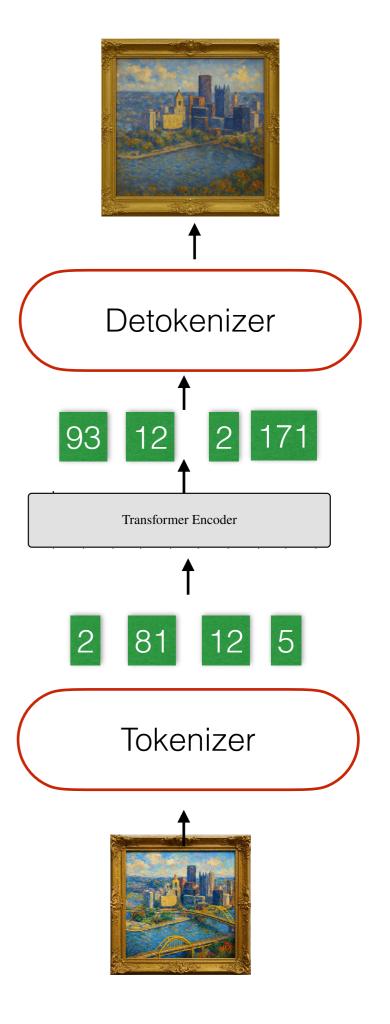




(a) Learned Frey Face manifold

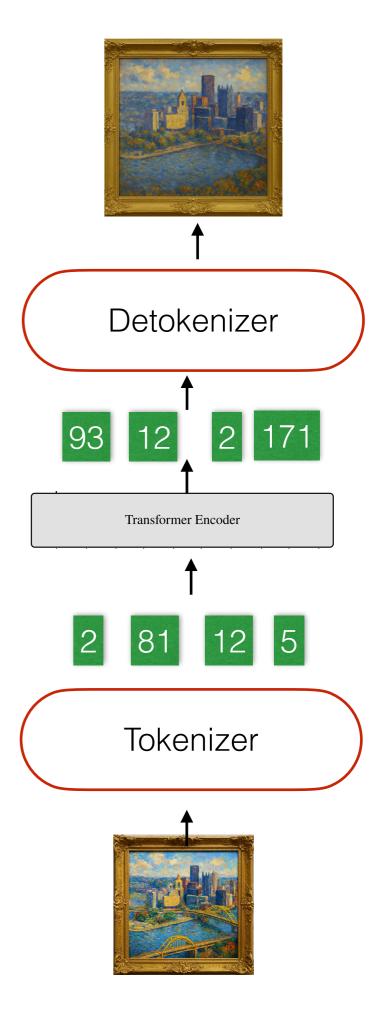
(b) Learned MNIST manifold

From continuous to discrete



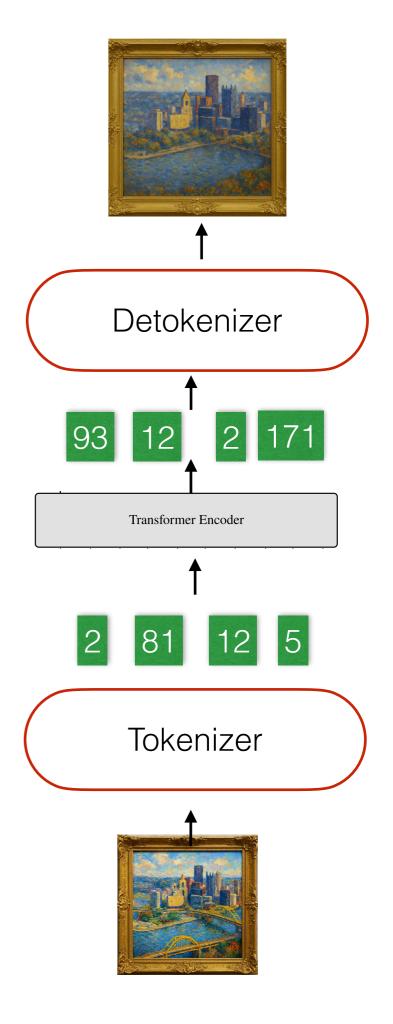
From continuous to discrete

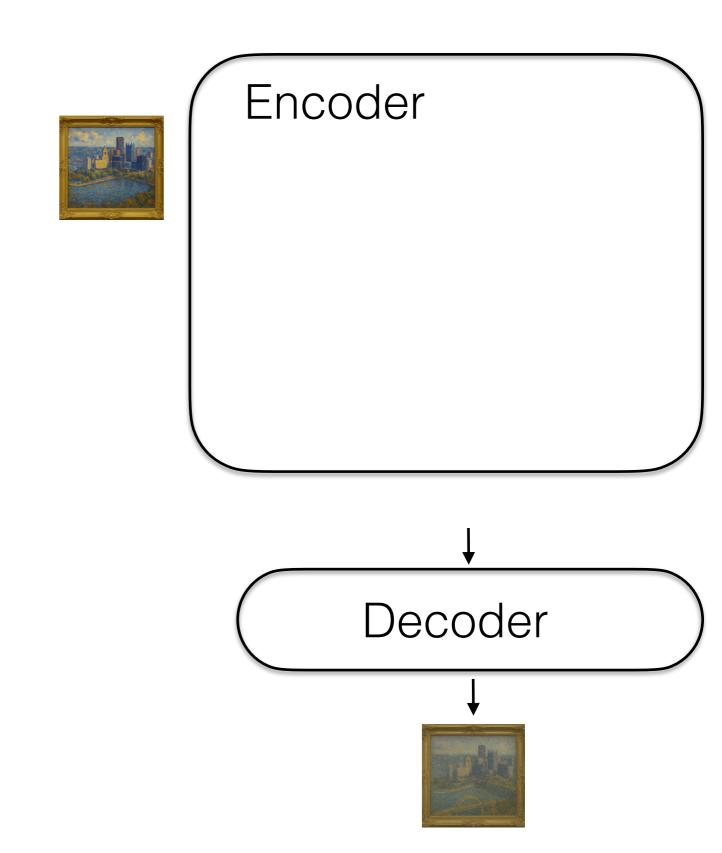
 Standard VAEs give us a way to encode and decode images using a continuous vector



From continuous to discrete

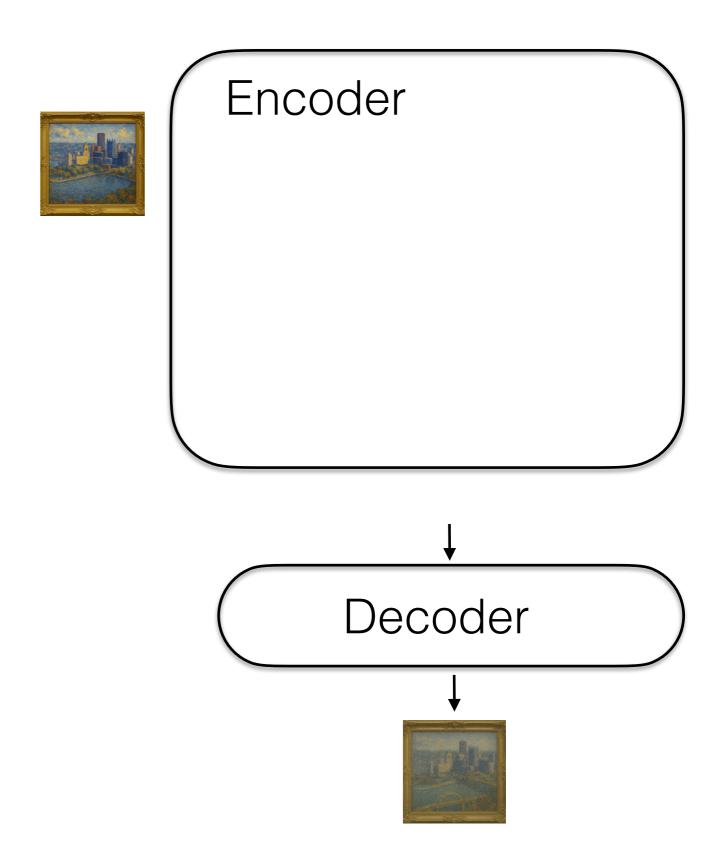
- Standard VAEs give us a way to encode and decode images using a continuous vector
- Idea: make a discrete VAE to let us:
 - encode an image as a sequence of discrete tokens
 - decode an image from a sequence of discrete tokens



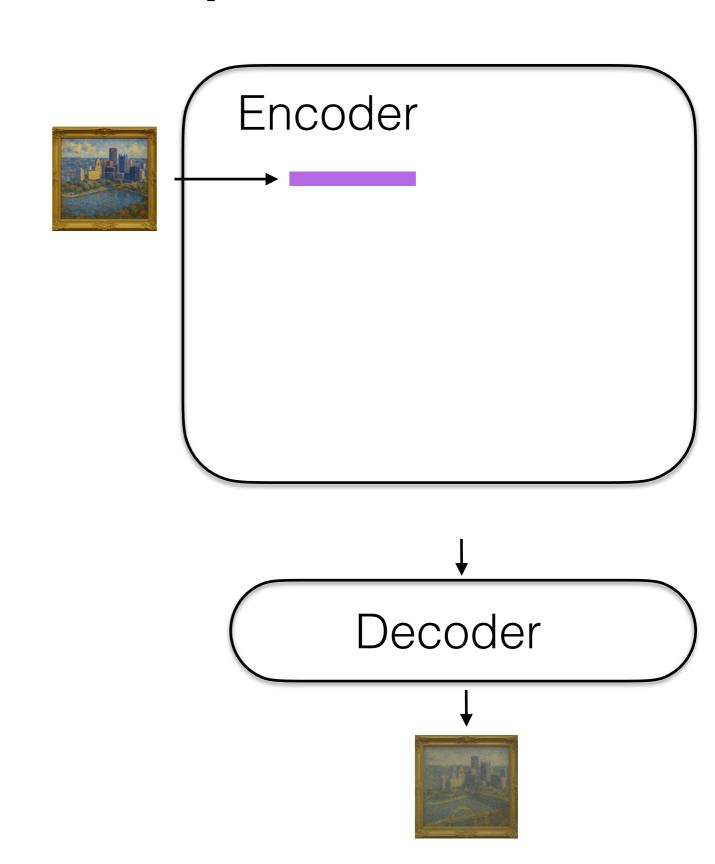


[van den Oord 2017]

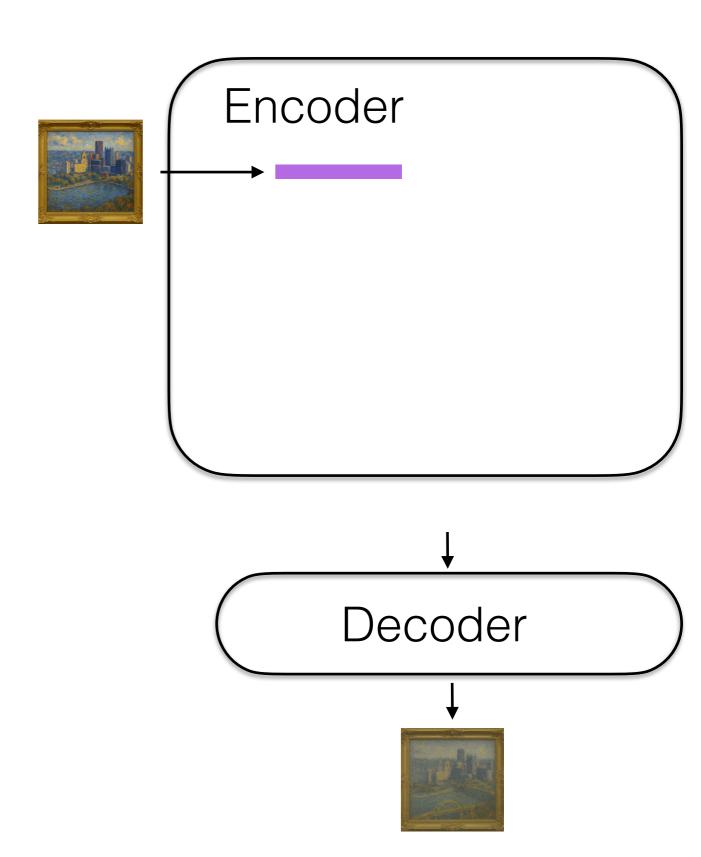
• Encoder: q(z | x)



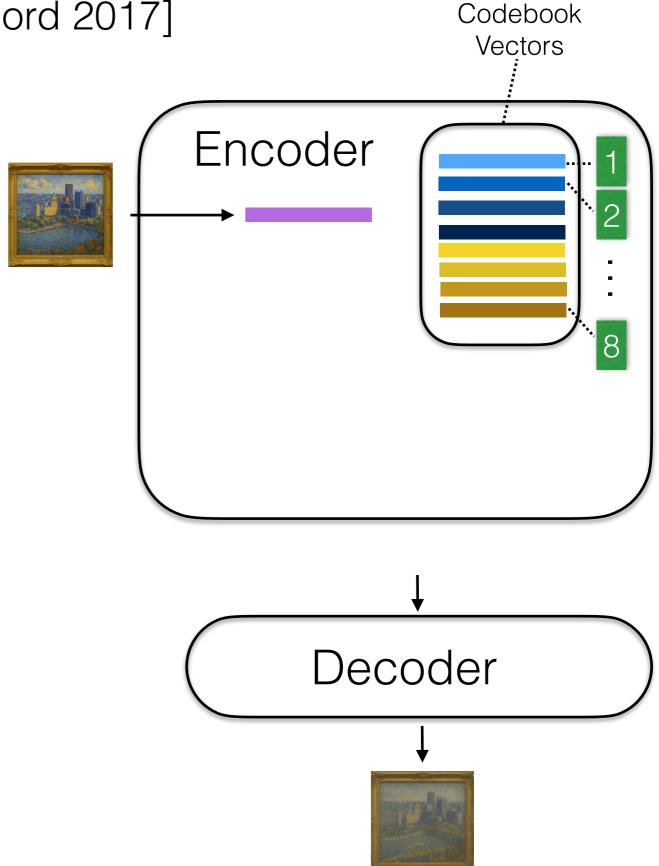
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 - $x \to z_e(x) \in \mathbb{R}^d$
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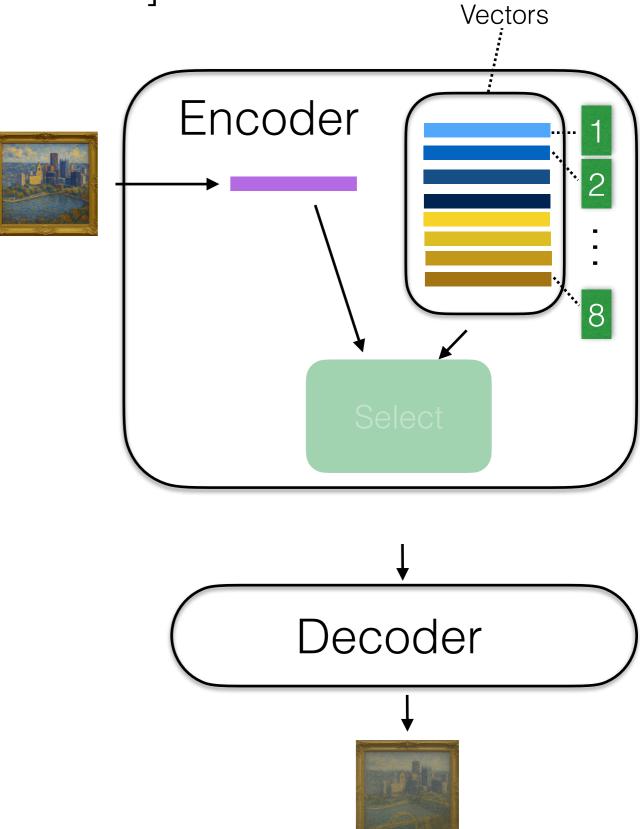


- Encoder: q(z | x)
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 - Compare $z_e(x)$ to a set of learned codebook vectors



[van den Oord 2017]

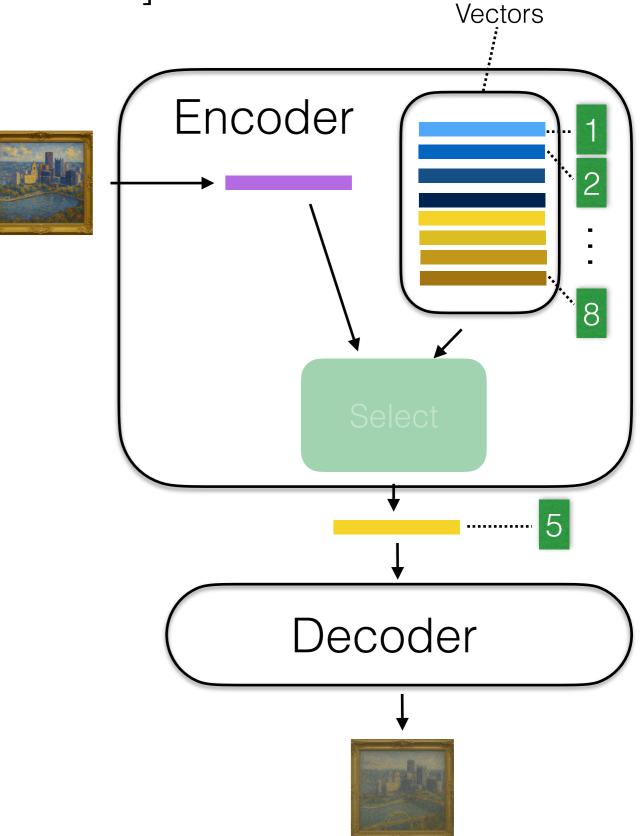
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 - $z_q(x) = e_{k^*}$, where $k^* = \arg\min_{j \in \{1, ..., K\}} \|z_e(x) e_j\|_2$



Codebook

[van den Oord 2017]

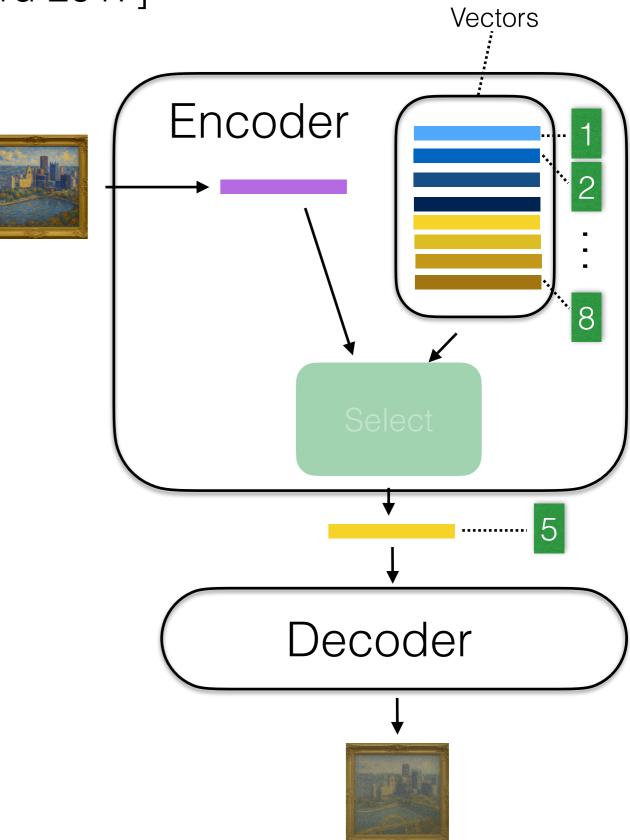
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 - $q(z = k \mid x) = \begin{cases} 1 & k = k^* \\ 0 & \text{otherwise} \end{cases}$



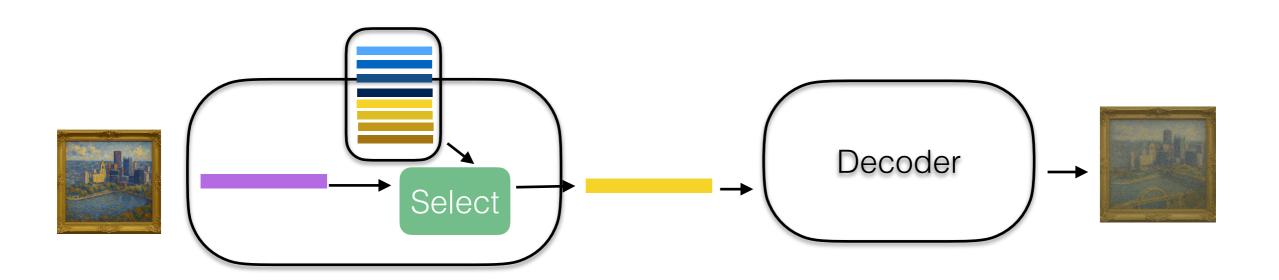
Codebook

[van den Oord 2017]

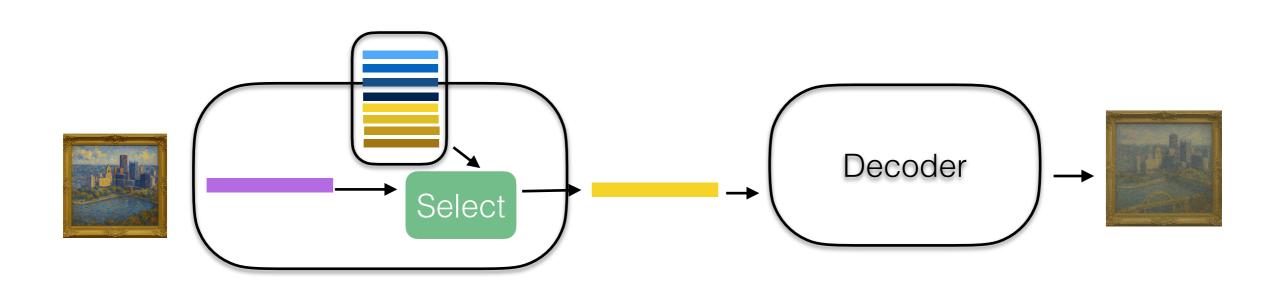
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- Decoder:
 - $p(x | z_q(x))$



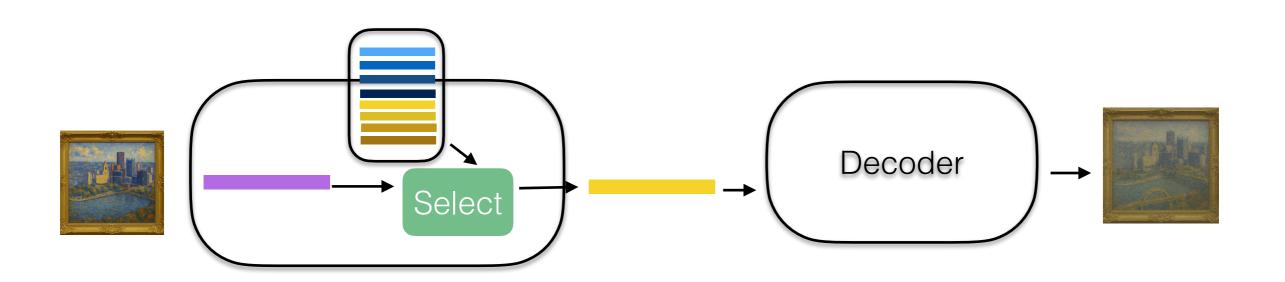
Codebook



• $\mathcal{L} = \log p(x | z_q(x)) + \|\operatorname{sg}[z_e(x)] - e\|_2^2 + \beta \|z_e(x) - \operatorname{sg}[e]\|_2^2$

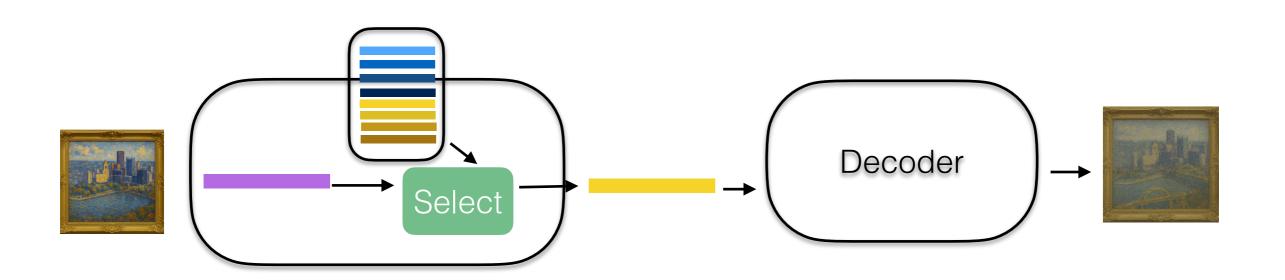


•
$$\mathcal{L} = \frac{\log p(x|z_q(x))}{\log p(x|z_q(x))} + \frac{\log |z_e(x)| - e|_2^2 + \beta ||z_e(x)| - \log |e|_2^2}{\log p(x|z_q(x))}$$
Reconstruction



•
$$\mathcal{L} = \log p(x | z_q(x)) + \| \operatorname{sg}[z_e(x)] - e \|_2^2 + \beta \| z_e(x) - \operatorname{sg}[e] \|_2^2$$

Reconstruction codebook embedding

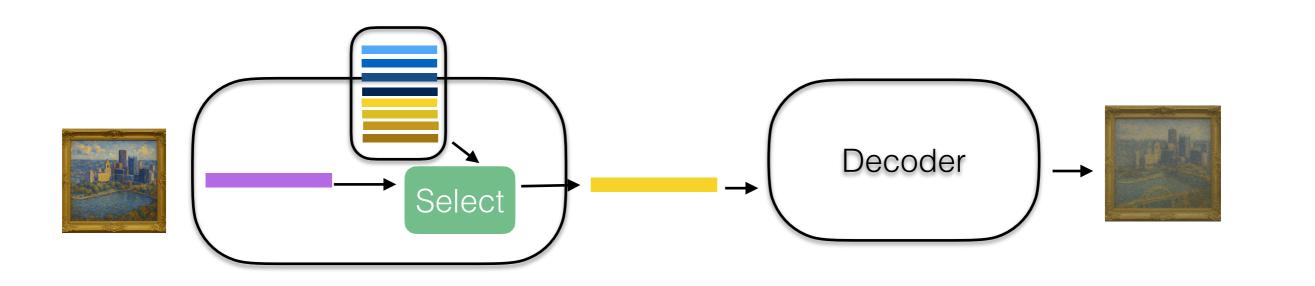


VQ-VAE training

•
$$\mathcal{L} = \log p(x \mid z_q(x)) + \| \operatorname{sg}[z_e(x)] - e \|_2^2 + \beta \| z_e(x) - \operatorname{sg}[e] \|_2^2$$

Update codebook embedding

Codebook embedding



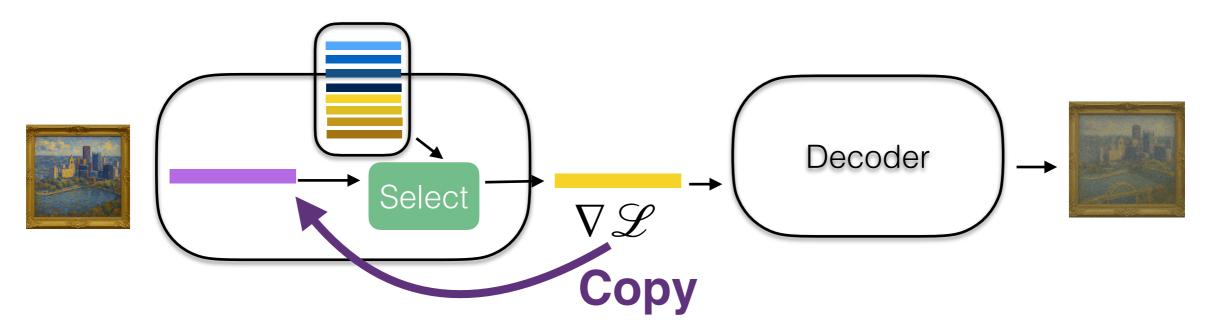
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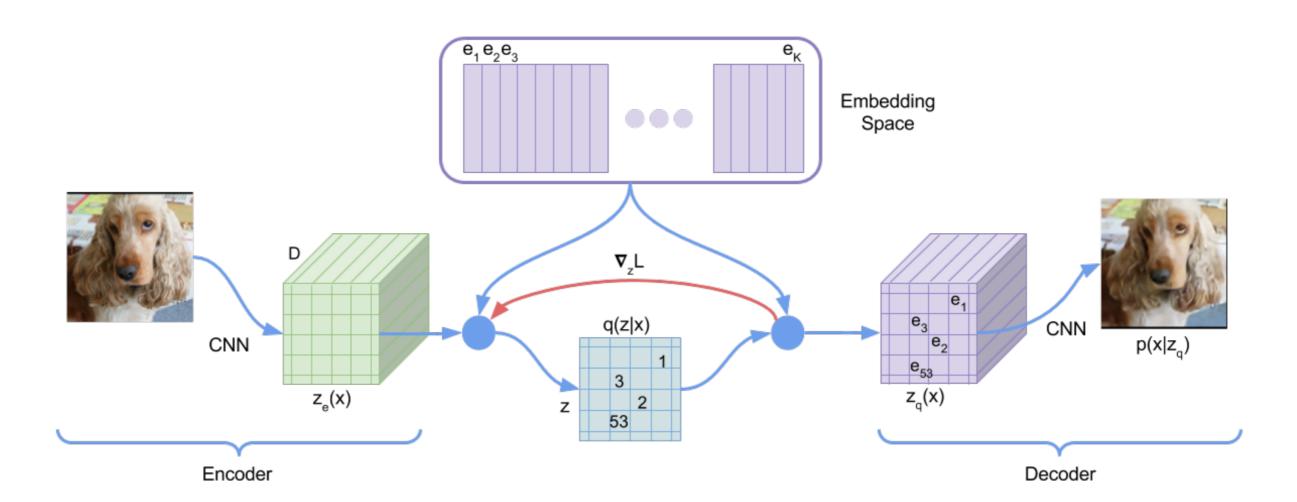
Update codebook embedding

Codebook embedding

 For reconstruction loss, use a straight-through gradient estimator since the codebook lookup is non-differentiable



VQ-VAE



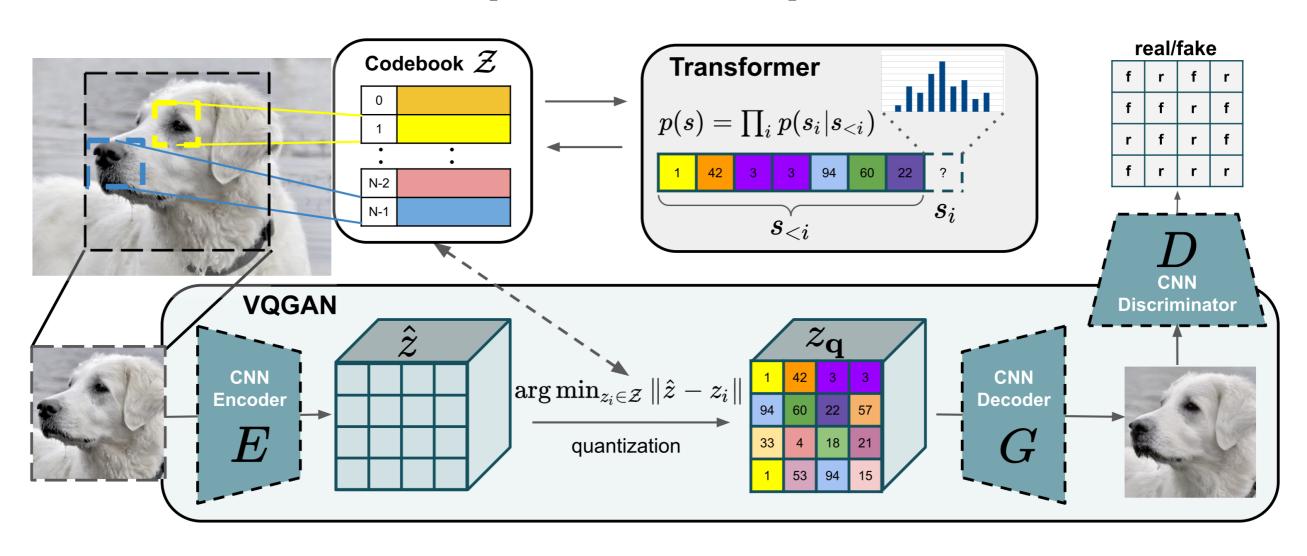
Example

DALL-E tokenizer

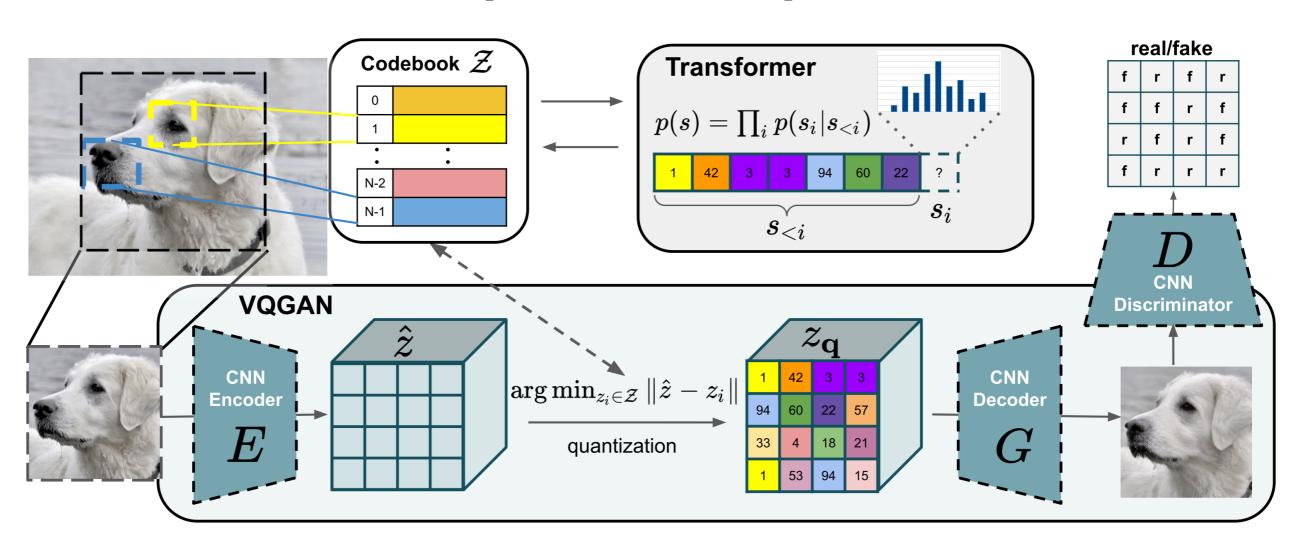


```
x_stats = dec(z).float()
 x_rec = unmap_pixels(torch.sigmoid(x_stats[:, :3]))
 x_rec = T.ToPILImage(mode='RGB')(x_rec[0])
 display_markdown('Reconstructed image:')
 display(x_rec)
✓ 0.3s
```

[Esser et al 2021]

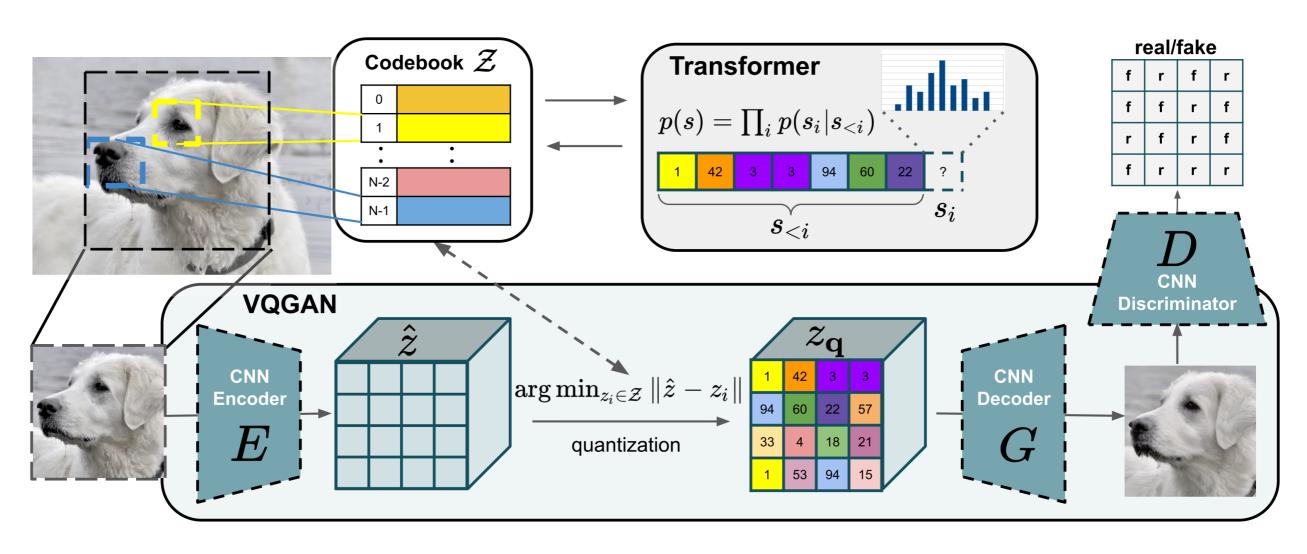


[Esser et al 2021]



Modify VQ-VAE objective: use a GAN objective and perceptual loss

[Esser et al 2021]



- Modify VQ-VAE objective: use a GAN objective and perceptual loss
- Train an autoregressive transformer ("language model") on the resulting discrete tokenized images. Generate images with it.

VQ-GAN [Esser et al 2021]

Training the encoder/decoder:

• $\hat{x} = G(\operatorname{select}(E(x)))$

- $\hat{x} = G(\operatorname{select}(E(x)))$
 - G: generator

VQ-GAN [Esser et al 2021]

- $\hat{x} = G(\operatorname{select}(E(x)))$
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 - G: generator
 - E: encoder
- $\mathcal{L}_{GAN} = \log D(x) + \log(1 D(\hat{x}))$
 - D: discriminator

[Esser et al 2021]

Training the transformer language model:

[Esser et al 2021]

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• Tokenize lots of images using the tokenizer (encoder) $x_{img} \rightarrow (x_1, x_2, ..., x_T)$

[Esser et al 2021]

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• Example $T: 32 \times 32 = 1024$

[Esser et al 2021]

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- Example $T: 32 \times 32 = 1024$
 - Much less than modeling pixels (256x256 = 65,536)!

[Esser et al 2021]

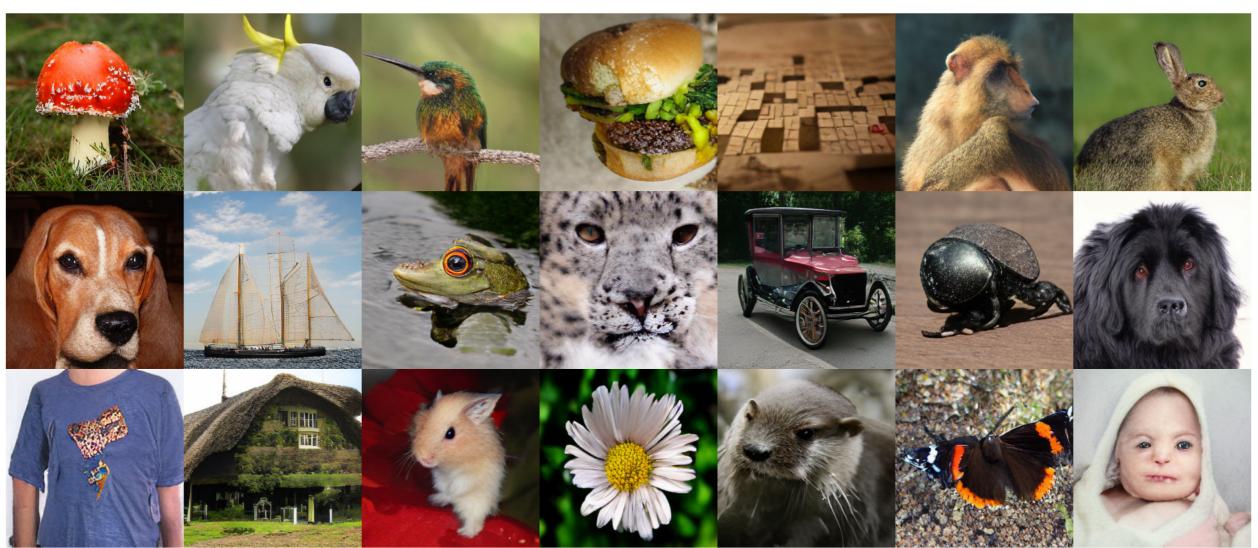


Figure 8. Samples from our class-conditional ImageNet model trained on 256×256 images.

[Esser et al 2021]

conditioning

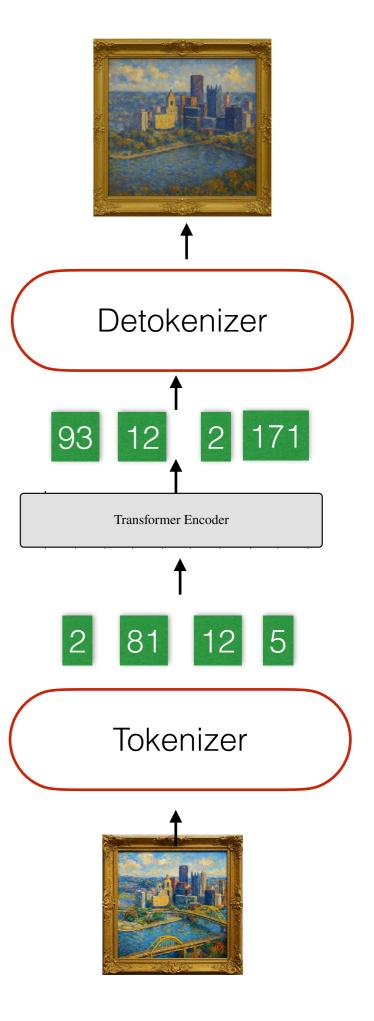
samples



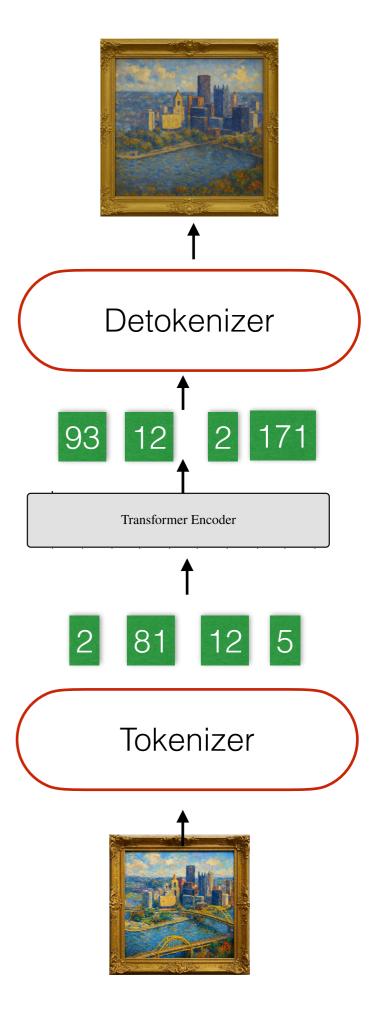




- Tokenizer: VQ-VAE/VQ-GAN encoder
- De-tokenizer: VQ-VAE/VQ-GAN decoder

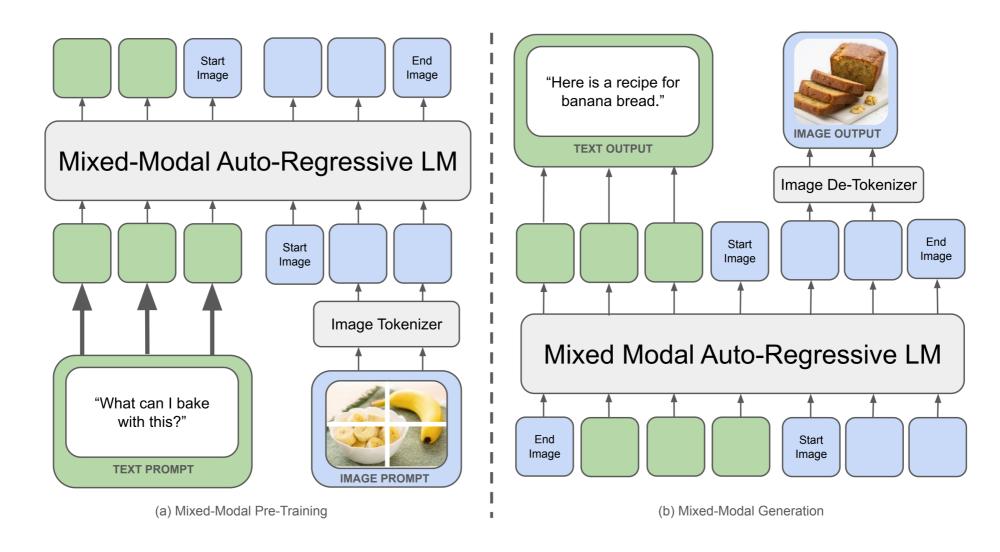


- Tokenizer: VQ-VAE/VQ-GAN encoder
- De-tokenizer: VQ-VAE/VQ-GAN decoder
- Next:
 - Add the tokens to a language model's vocabulary
 - Train / fine-tune the model on both text and image tokens



Example: Chameleon

[Meta 2024]



- Train a VQ-GAN tokenizer/de-tokenizer
- Then train a language model on 10T tokens

Example: Chameleon

[Meta 2024]



**Prompt: ** While chameleons are masters of camouflage in the natural world, let's see how they might fare in a man-made setting.

- 1. Analyze the colors, patterns, and textures in this image and identify the most challenging spot for a chameleon to blend in.
- 2. Then generate an image of a chameleon with the optimal pattern to camouflage itself.
- 3. Then, rate and explain how successful each attempt is on a scale from 1-10.

Response: The image is of a stop sign in a forested area, with some sunlight filtering through the trees. The sign has a red octagonal shape with a white border and the word "STOP" written in white letters. In the background, there are green leaves and trees.

Challenging Spot for a Chameleon: The stop sign would be the most challenging spot for a chameleon to blend in due to its bright red color and bold white letters, which would stand out in the forested environment.

Optimal Pattern for Camouflage: To camouflage itself on the stop sign, a chameleon would need to have a pattern that would break up its outline and make it less conspicuous. A pattern with shades

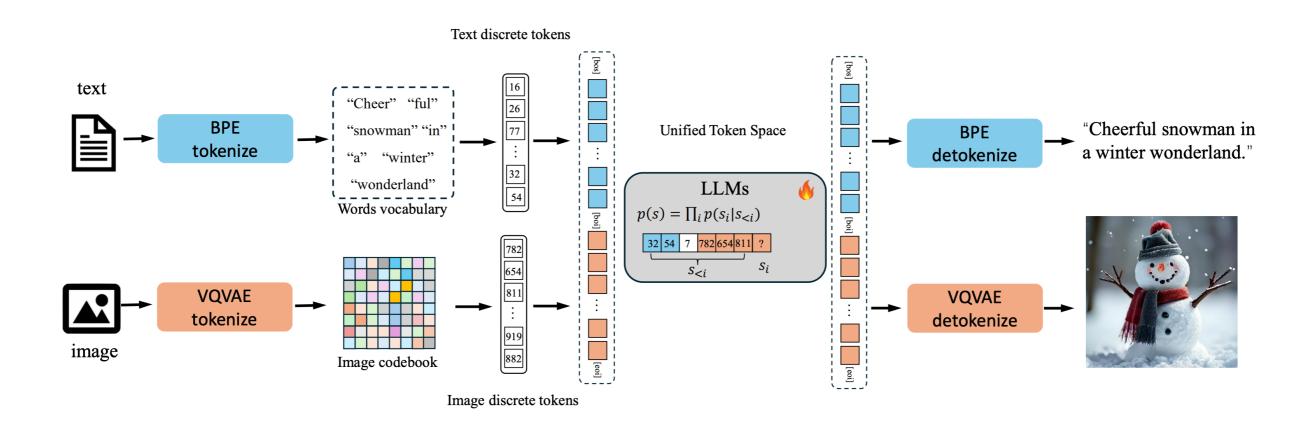


of brown and red would help the chameleon blend in more effectively. Additionally, a mottled or dappled pattern would help to scatter light and further reduce the chameleon's visibility.

Rating and Explanation: A rating of 2/10 would be given for the chameleon's ability to blend in on the stop sign. While the chameleon's green and brown pattern helps to break up its outline, the bright red color of the stop sign will still make it stand out in the forested environment.

Example: Liquid

[Wu et al 2024]

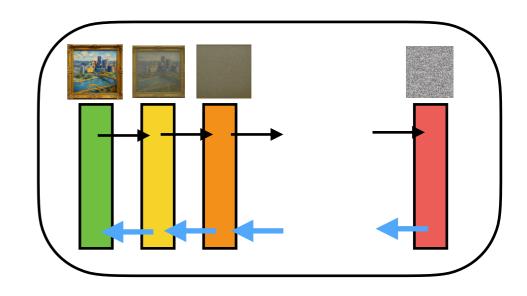


- VQ-GAN tokenizer
- Fine-tune LLMs

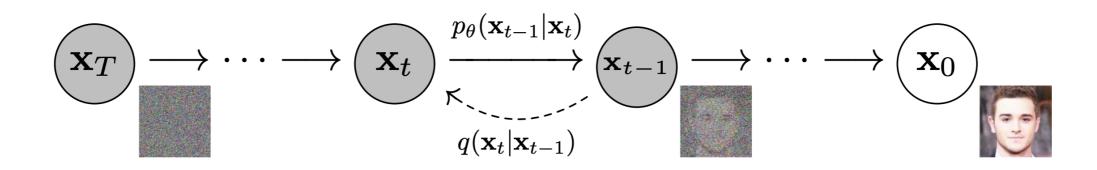
Other methods

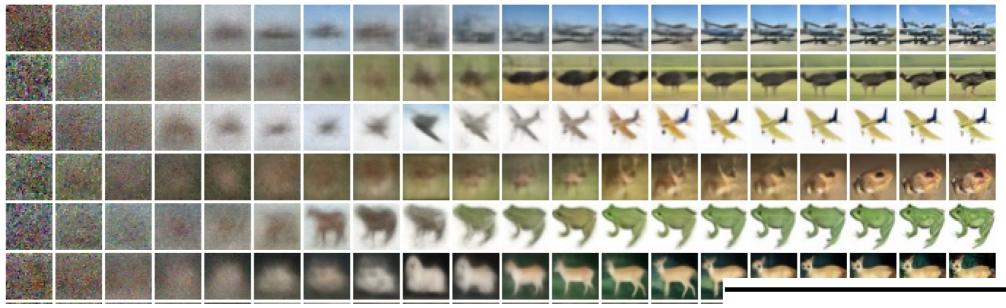
- A big missing piece: diffusion!
- Many text-to-image models
- An extremely quick overview of some early references (up to early 2022)

Diffusion

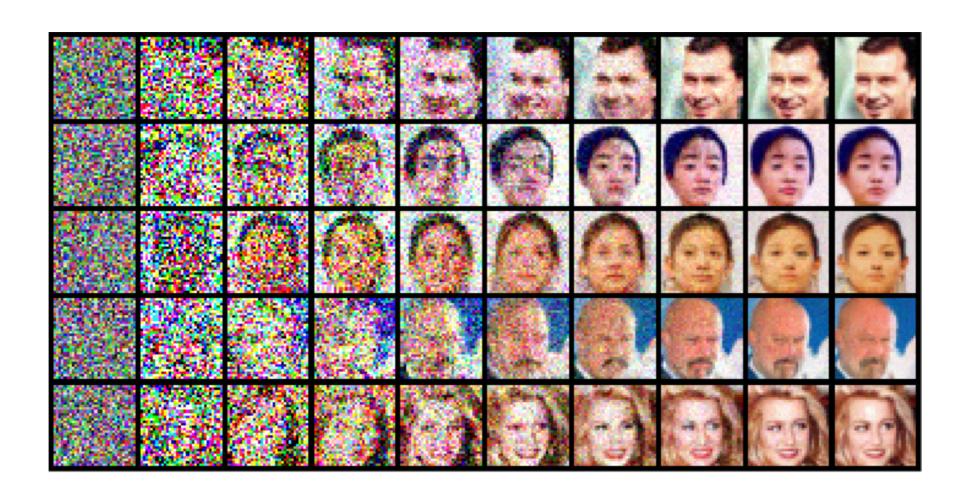


Denoising Diffusion Probabilistic Models [Ho et al 2020]





Score-based generative models [Song & Ermon 2020]



Generative Modeling by Estimating Gradients of the Data Distribution

Diffusion Models Beat GANs [Dhariwal & Nichol 2021]



Text-Guided Diffusion Models [Nichol et al 2022]



"a hedgehog using a calculator"



"a corgi wearing a red bowtie and a purple party hat"



"robots meditating in a vipassana retreat"



"a fall landscape with a small cottage next to a lake"

GLIDE: Towards Photorealistic Image Generation and Editing with Text-Guided Diffusion Models

DALL-E 2 [Ramesh et al 2022]



vibrant portrait painting of Salvador Dalí with a robotic half face



a shiba inu wearing a beret and black turtleneck



a close up of a handpalm with leaves growing from it

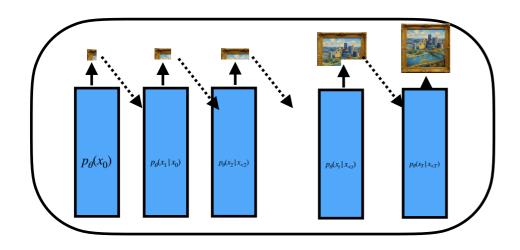
Hierarchical Text-Conditional Image Generation with CLIP Latents

Aditya Ramesh* OpenAI aramesh@openai.com Prafulla Dhariwal* OpenAI prafulla@openai.com Alex Nichol* OpenAI alex@openai.com

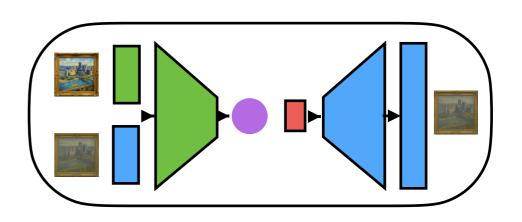
Casey Chu*
OpenAI
casey@openai.com

Mark Chen OpenAI mark@openai.com

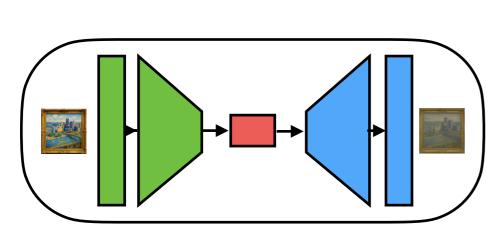
Autoregressive



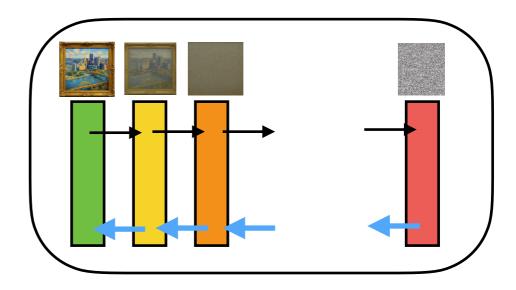
GAN

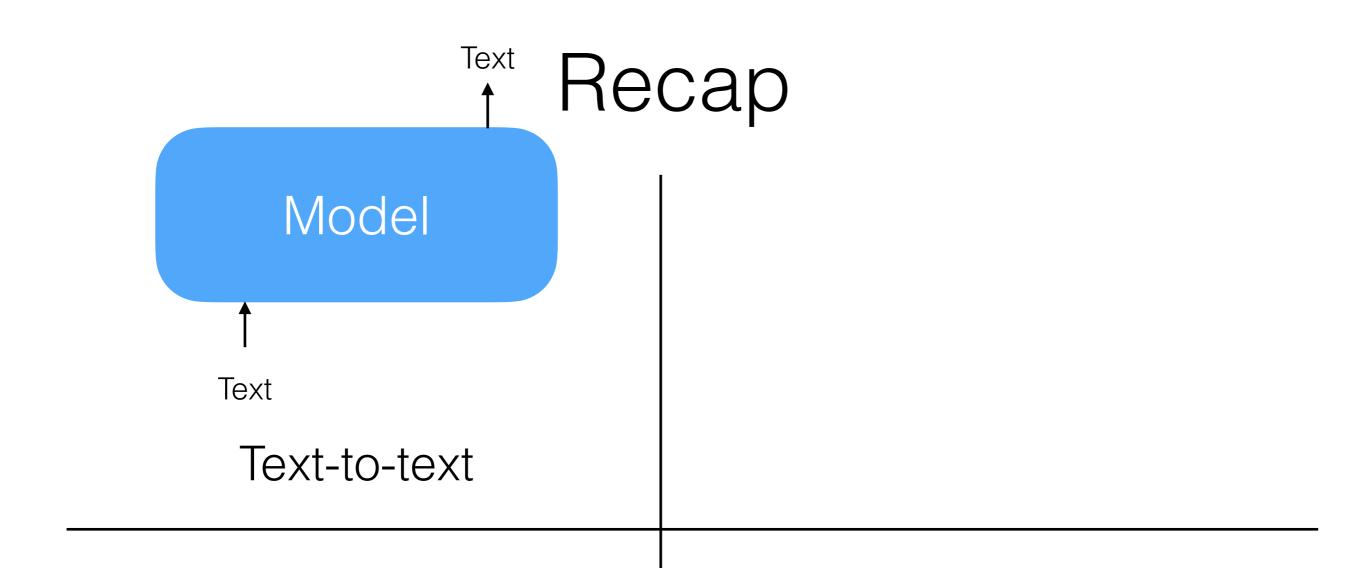


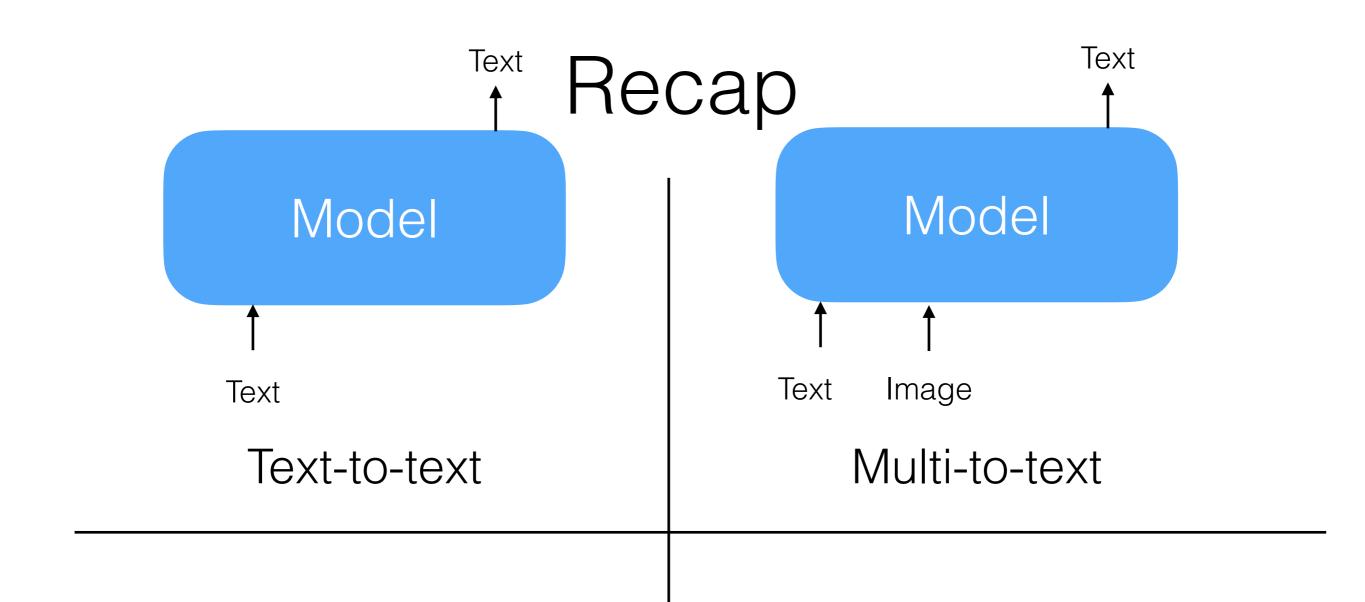
VAE

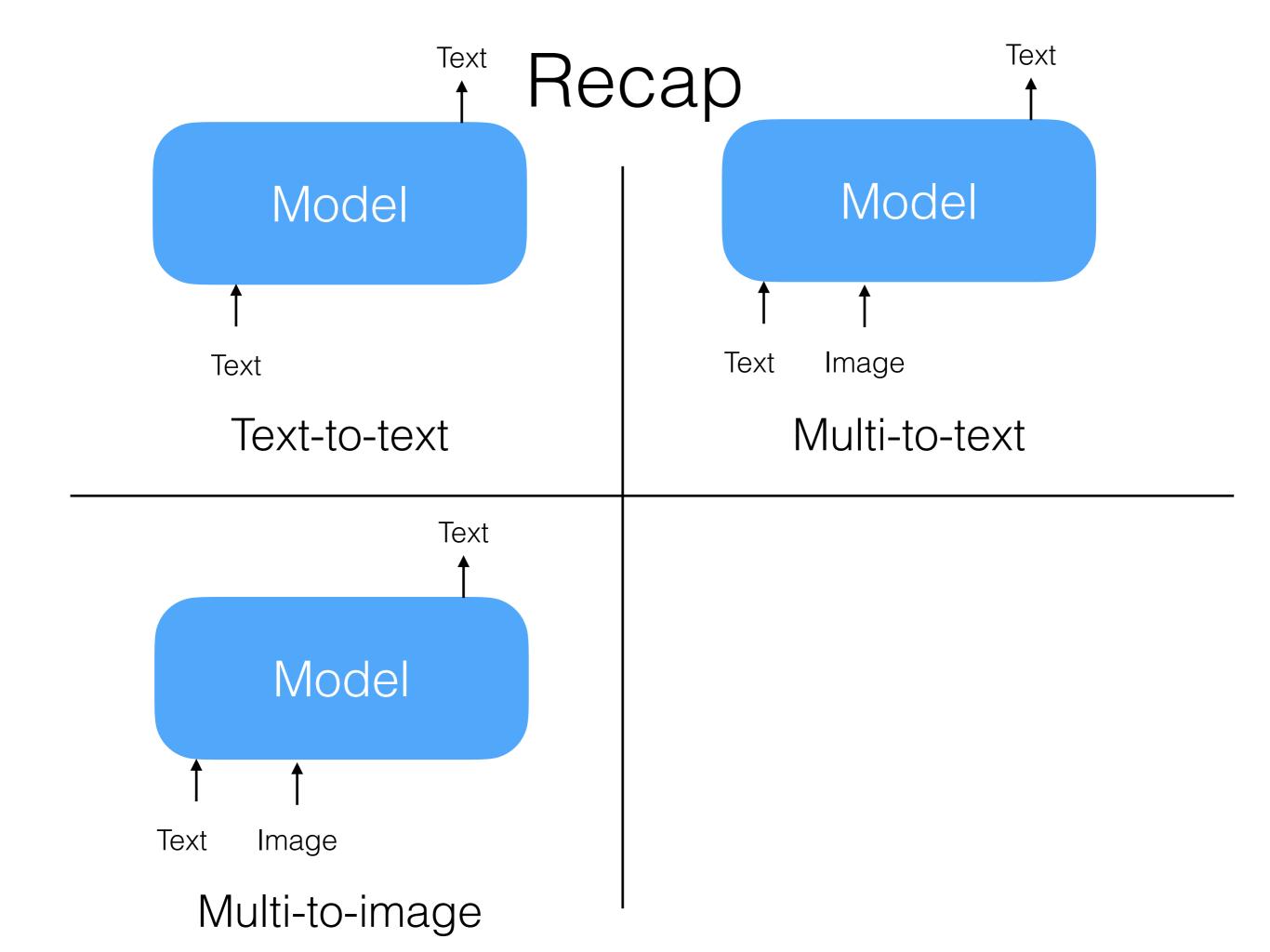


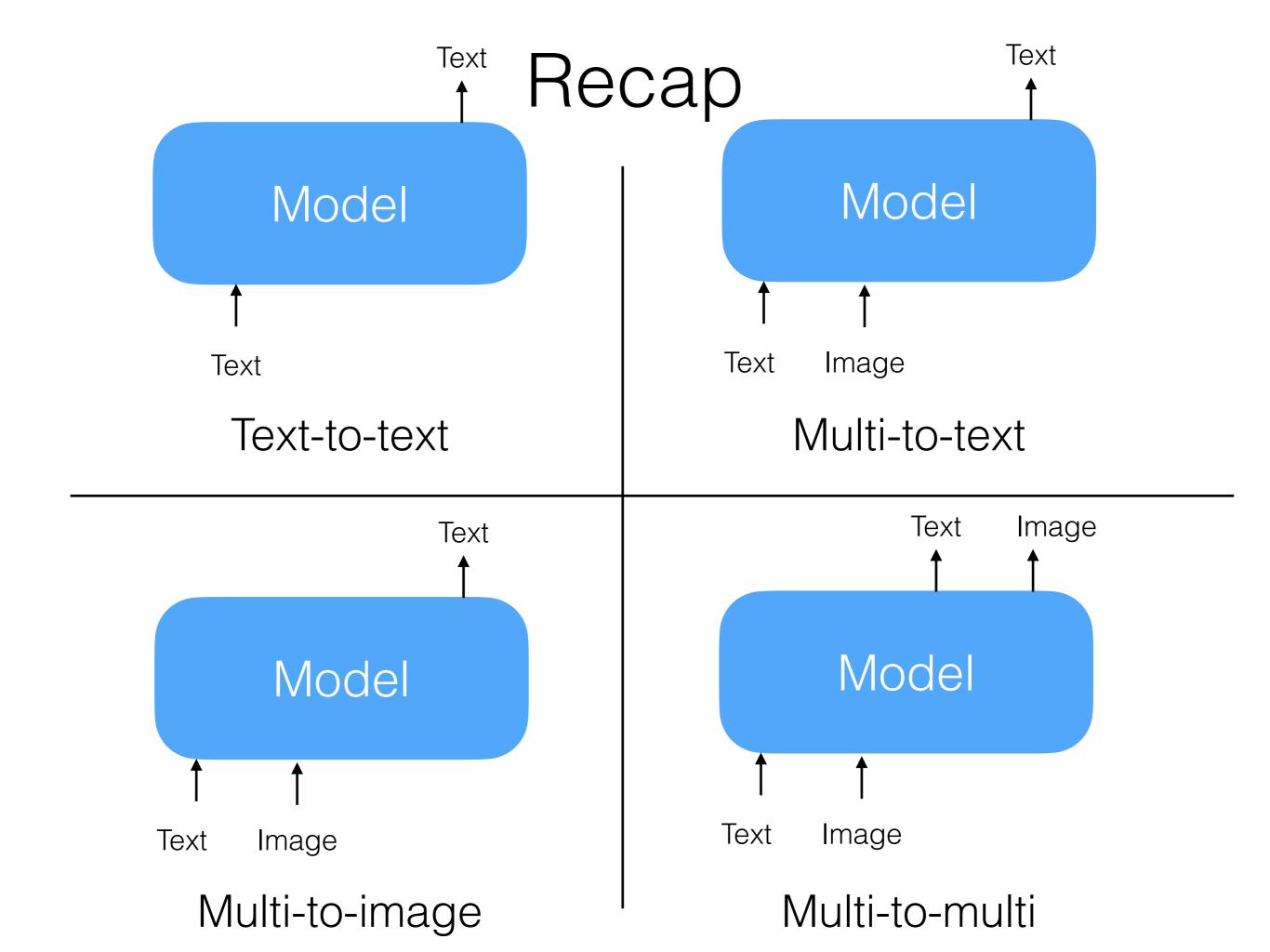
Diffusion

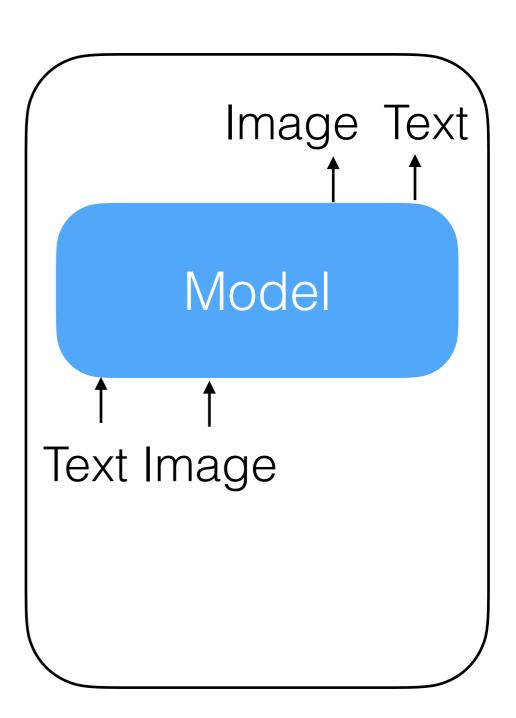




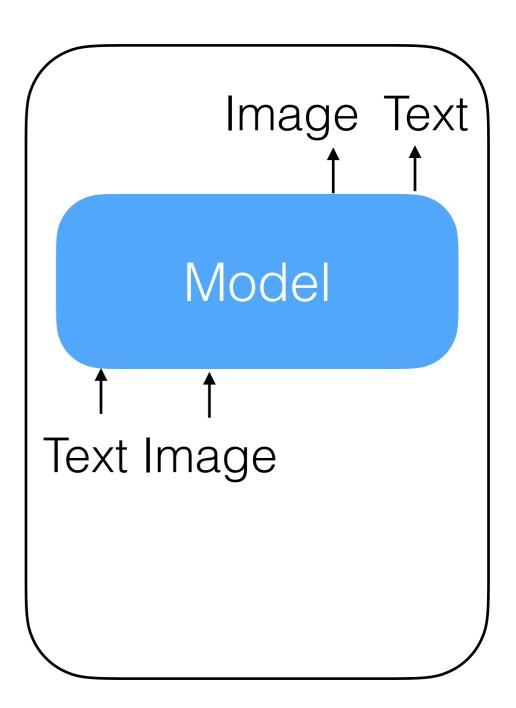




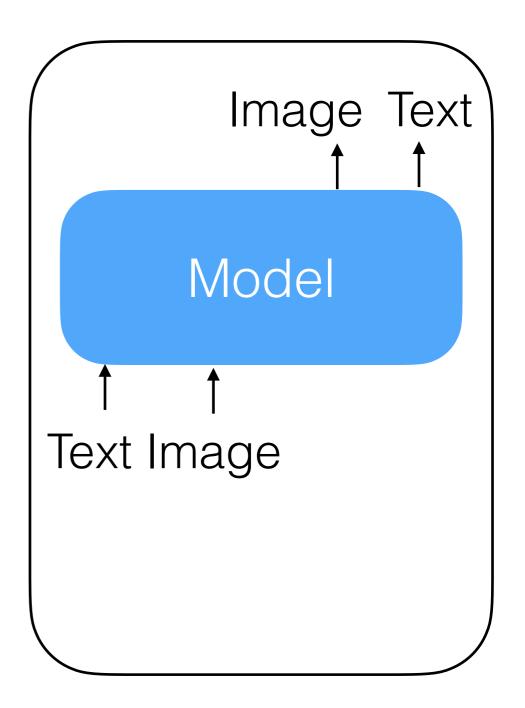




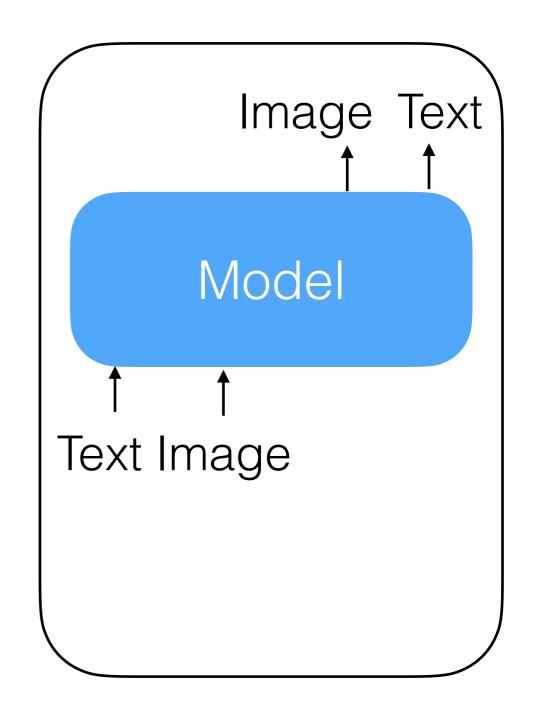
 Basic generative modeling paradigms



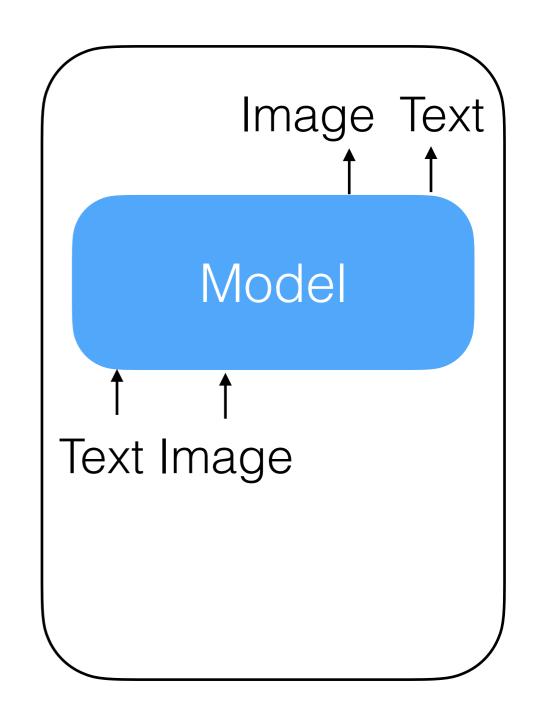
- Basic generative modeling paradigms
- Autoregressive modeling of pixels



- Basic generative modeling paradigms
- Autoregressive modeling of pixels
- Autoregressive modeling of "image tokens"



- Basic generative modeling paradigms
- Autoregressive modeling of pixels
- Autoregressive modeling of "image tokens"
- Quick tour of diffusion references



Thank you!